# Real-time monitoring of harbour porpoise activity around construction sites using the wireless detection system (WDS)

Bio **P** 

Consult

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## Pile driving noise can harm marine mammals

Standard method to avoid injury (before piling):









#### Standard efficiency control



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#### Why using an online detection system ?

#### Sealscarer have been shown to deter successfully, but:

- Not all individuals may react with avoidance behaviour.
- Animals may get used to deterrents.
- Deterrence stops during piling.
- Deterrence might be reduced.
- Noise mitigation might not reach required levels (or not be requested (UK, DK, F)).
- POD data are available only after recovery of PODs.
- Other methods (Marine Mammal Observer) are restricted to daylight and very calm sea.



1. Is the WDS a reliable system detecting the presence of harbour porpoises at offshore construction sites ?

2. How is the performance of the WDS?

→Detection radius of a single WDS buoy
→in comparison to the established device, the CPOD

#### Risks:

1. Porpoises maybe missed and exposed to high noise levels.

2. False positives interfer with construction process.







WDS (up to 9 buoys): 41 pilings  $\rightarrow$  28 with detections (68%)

 $\rightarrow$  15 detections during pile driving: additional deterrence



### 1. WDS – a reliable system during pile driving



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### 2. Performance of a single WDS buoy: detection range



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#### **Detection probability**



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mean maximum detection radius:

CPOD: 32 tracks: 106 ± 44 m

WDS: 35 tracks: 140 ± 79 m (only clicks as trains)

52 tracks: 194 ± 97 m (single clicks)



#### Detection range only within 200 m

80 porpoise tracks within 200 m (average duration 321 sec)

WDS: 39 tracks (48.8 %)

CPOD: 32 tracks (40 %)

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only WDS: 17 tracks (21.3 %)

only CPOD: 10 tracks (12.5 %)



both: 22 tracks (27.5 %)

seconds porpoises spent in 200m distance

# 50% of all animals were detected after:WDS: 4:31 minCPOD: 6:38 min

#### **1.** Advantages of the WDS at NSO:

✓ WDS detected porpoises: animals were often present shortly before and after pile driving.

✓ A good spatial coverage of impact area could be achieved: a lot more detections by the 9 WDS buoys compared to two C-PODs.

 ✓ Real-time detection during pile driving allowed immediate use (and control) of further deterrence.

# Protection of harbour porpoises to harmful noise could be improved.



#### 2. Performance of the WDS proved by visual observations

✓ Theoretical detection probability approaches zero at 200 m for both devices (,trains') and 350m for WDS (single clicks).

✓ Mean measured maximum detection range of WDS: 194m (CPOD: 106m).

✓ 50% of all animals within 200m are recorded after 4.5 minutes (>2min better than CPODs).

✓ WDS also records single clicks.

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#### Outlook

#### **Real-time monitoring**

- offers great potential to protect cetaceans from harmful noise emissions - not only during pile driving
- With knowledge of the detection range of WDS buoys, the deployment design can be adapted to improve overall detection probability.



# Many thanks to



## and to all persons involved in the study



