
Signal reconstruction – An alternative approach for wind turbine monitoring

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Content

1. Monitoring wind turbine signals
2. Normal behaviour models
3. Data for analysis
4. Neural networks & stochastic approach
5. Results
6. Conclusions & outlook

1. Monitoring signals

Motivation

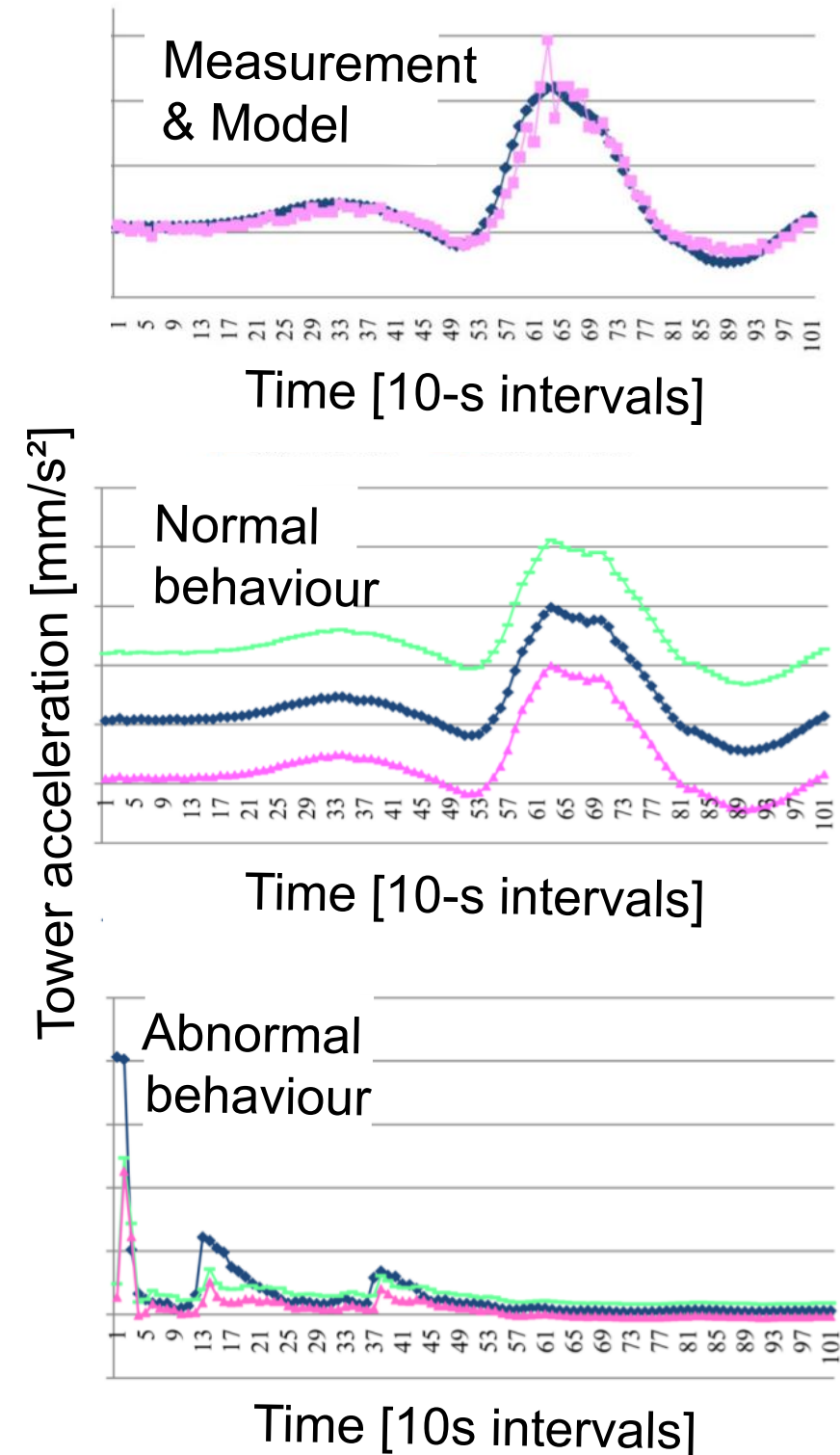
- Cost effective evaluation of wind turbine health

Utilisation

- Difference between measurements and expected behaviour is investigated to detect anomalies

Development

- 'Normal behaviour' models are created using available signals (with neural networks)



Monitoring wind turbine vibration
Based on SCADA data (Zhang, 2012)

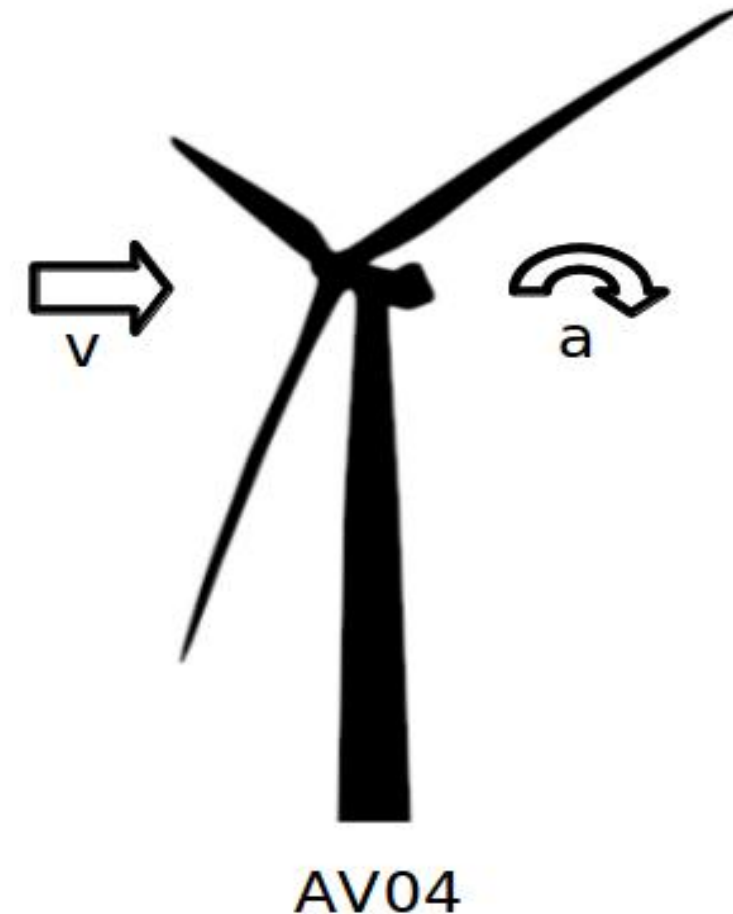
2. Normal behaviour model

Motivation

- Can we use the stochastic approach to develop a suitable normal behaviour model?

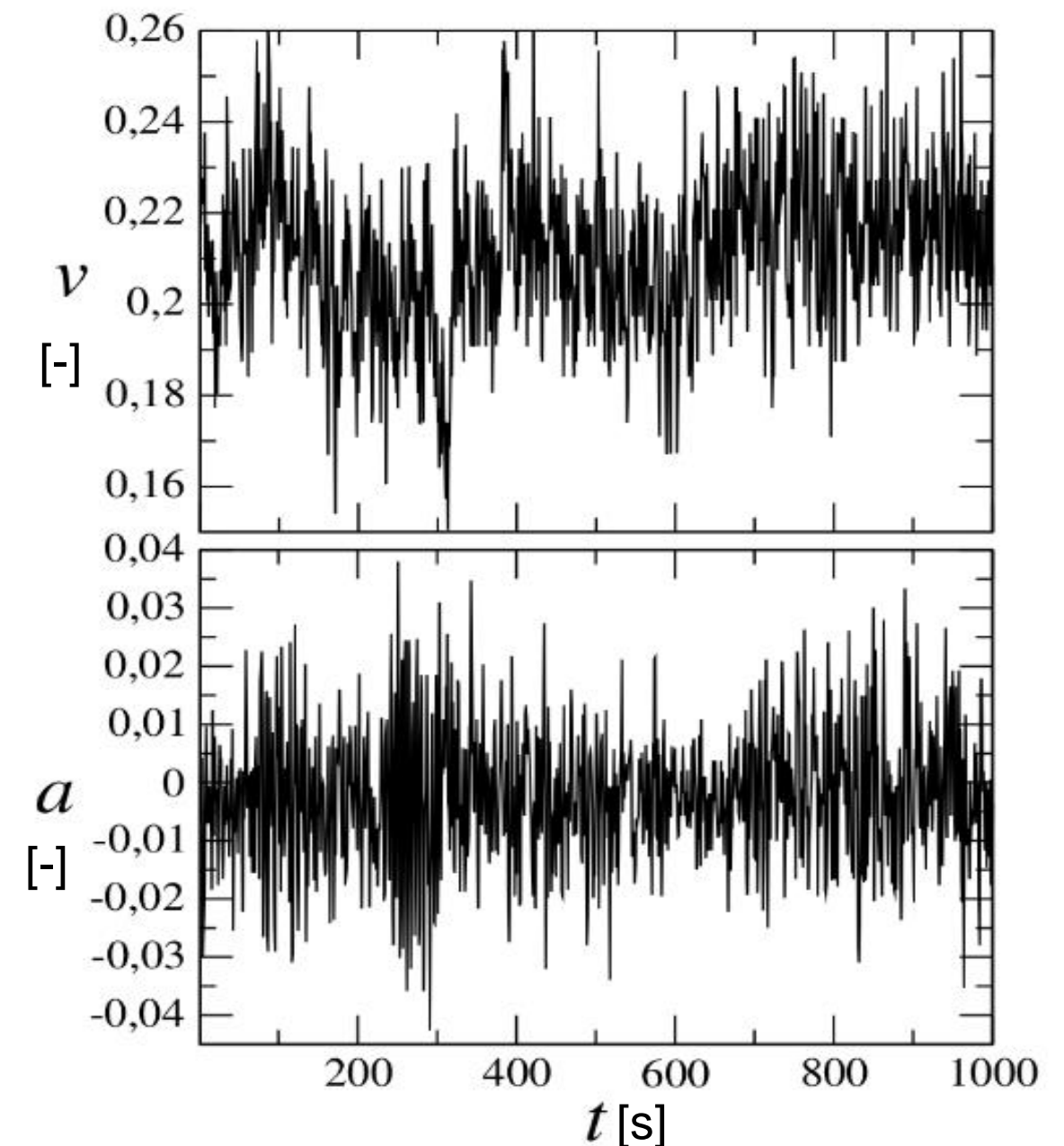
Methodology

- Investigate tower top acceleration with wind speed. Use data from turbine AV04
- Create a 'normal behaviour' model with neural network
- Repeat process with stochastic approach
- Compare models, response & report out



3. Data for analysis

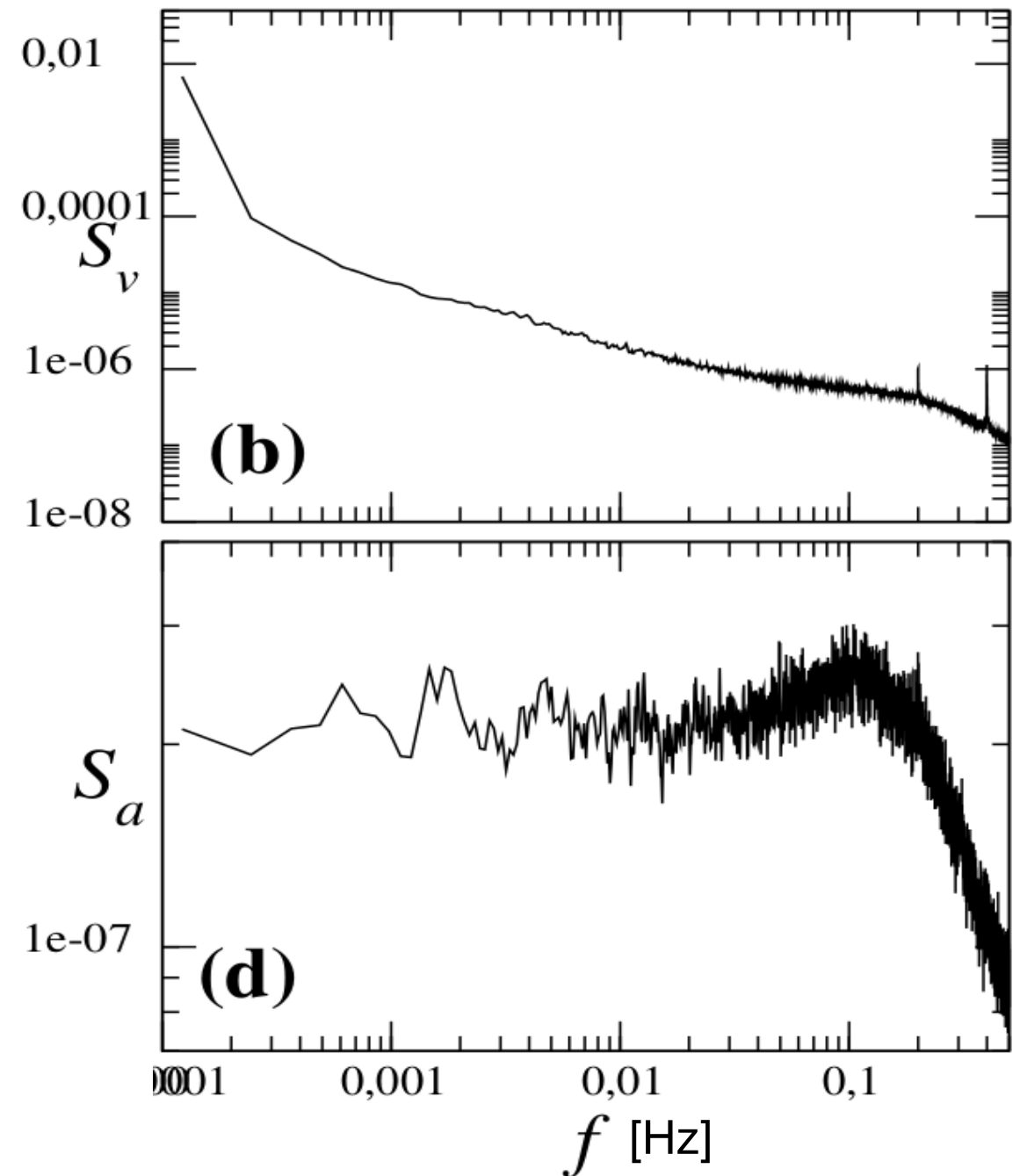
- Wind turbine AV04
- Target signal: tower top acceleration (a) [-]
- Predictor signal: wind speed (v)
- Data sets:
 - Development – October 2014
 - Test – November 2014
- Presented signals are normalised



Example of velocity (v) and acceleration (a)

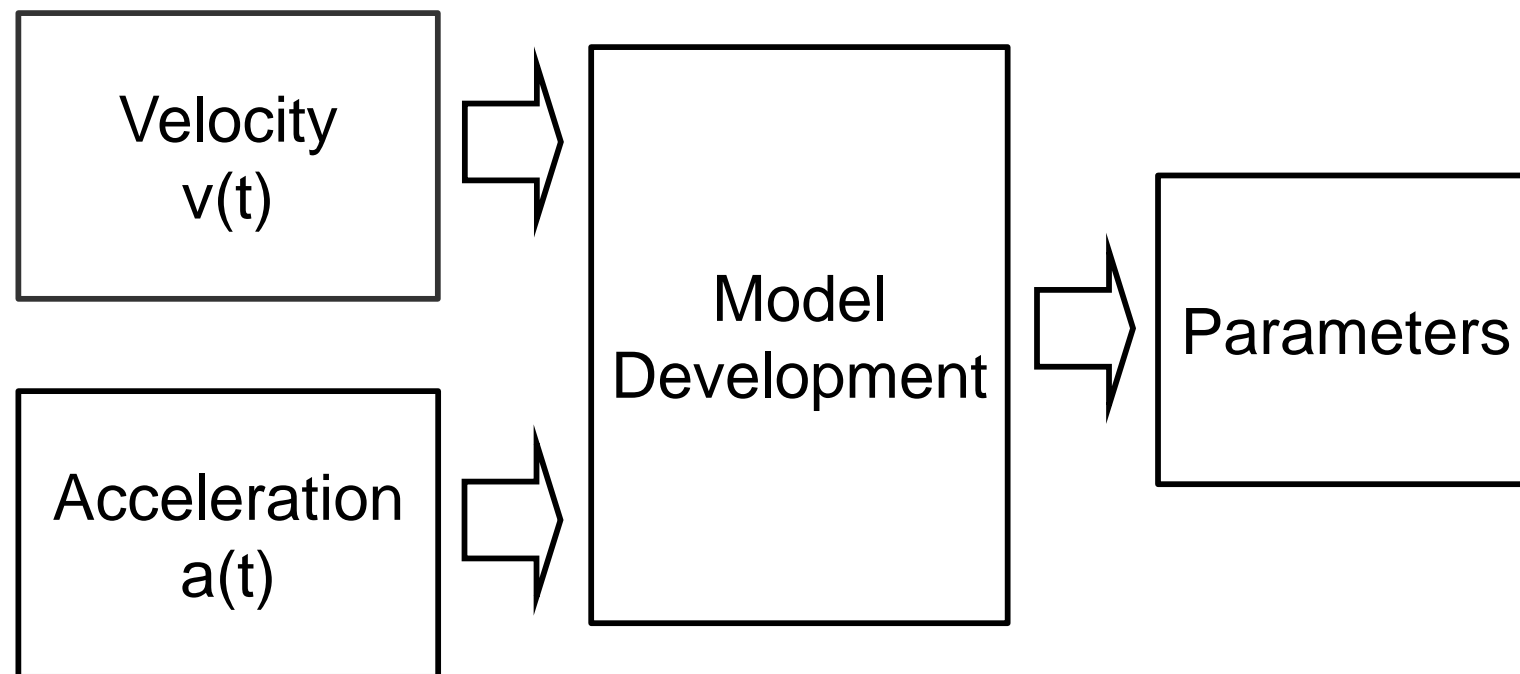
3. Data for analysis

- Wind turbine AV04
- Target signal: tower top acceleration (a)
- Predictor signal: wind speed (v)
- Data sets:
 - Development – October 2014
 - Test – November 2014
- 1 Hz sampling data



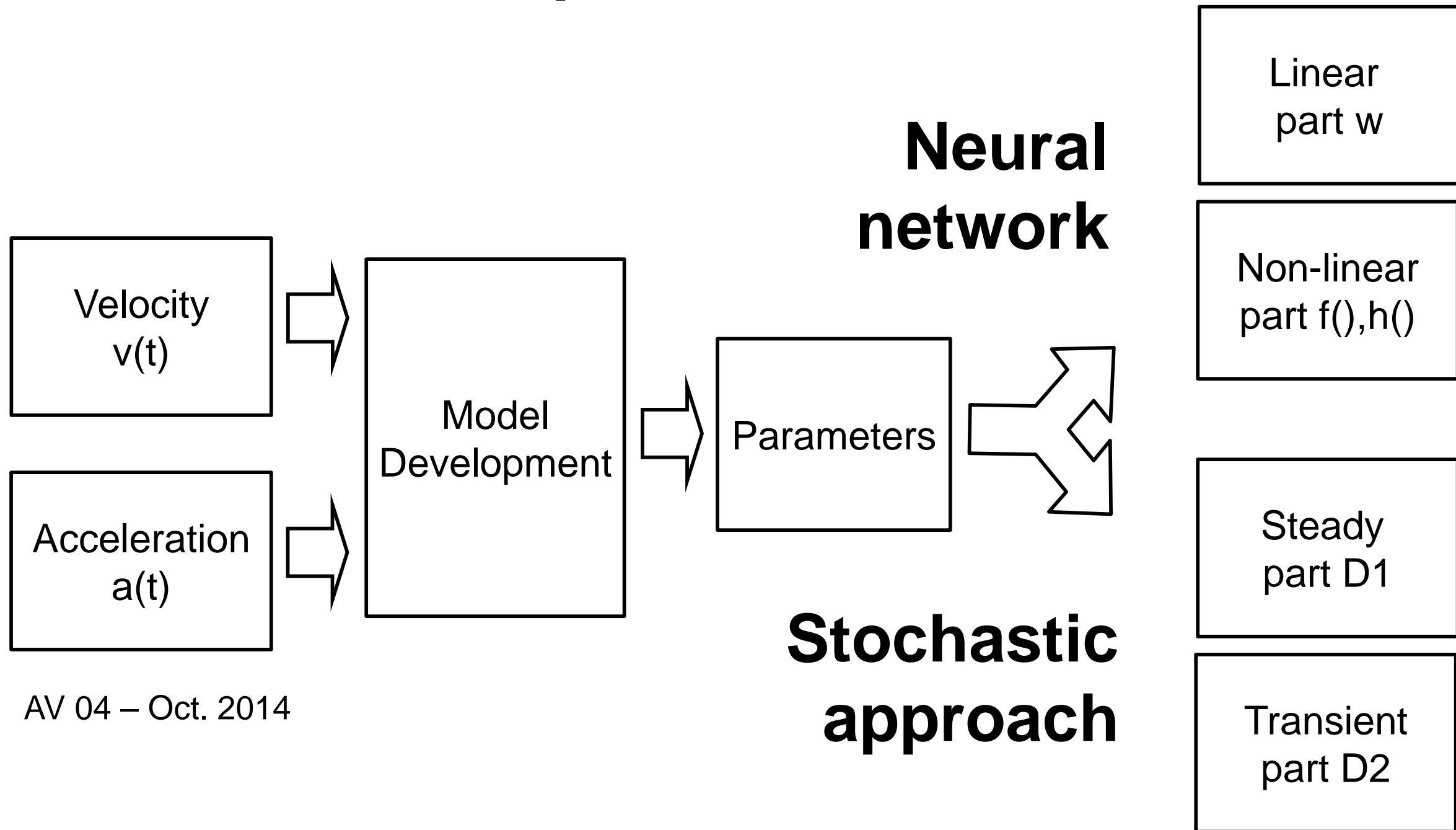
Example of velocity (v) and acceleration (a)

4. Models development



AV 04 – Oct. 2014

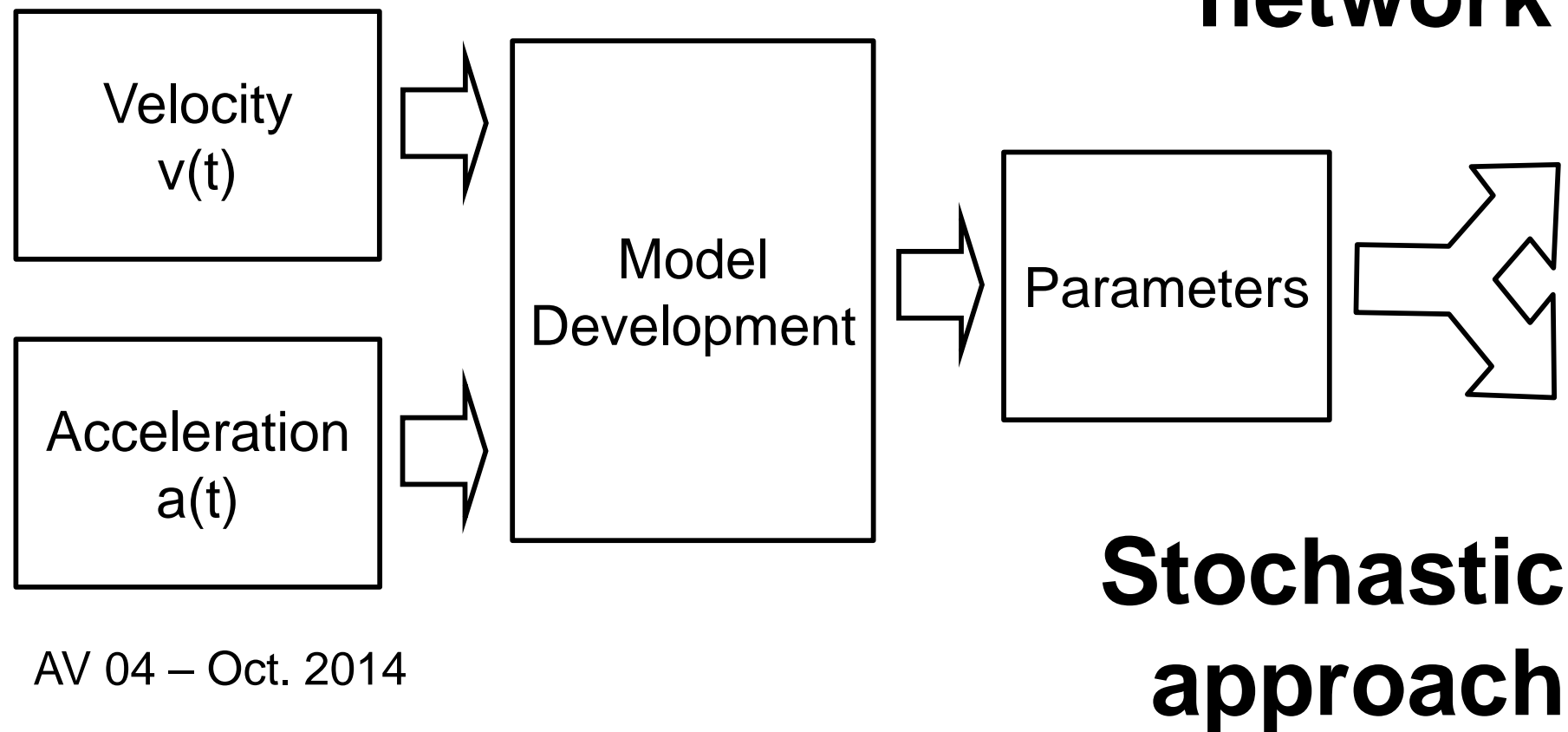
4. Models development



AV 04 – Oct. 2014

4. Models development

$$\hat{y}(x, w) = f\left(\sum_{j=0}^{n_h} \omega_j h\left(\sum_{i=0}^{n_i} \omega_{ji} x_i\right)\right)$$



AV 04 – Oct. 2014

Linear
part w

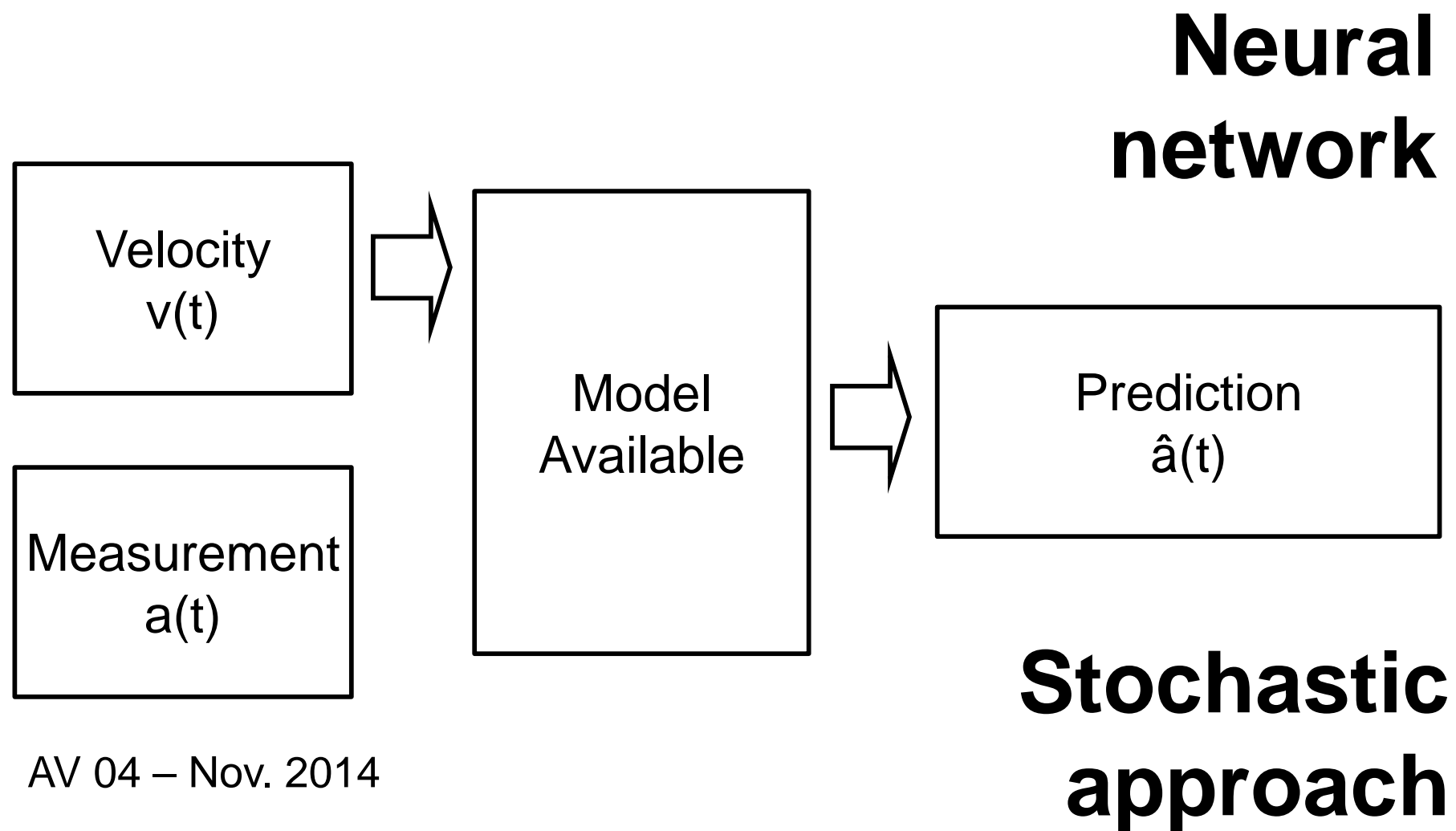
Non-linear
part f(),h()

Steady
part D1

Transient
part D2

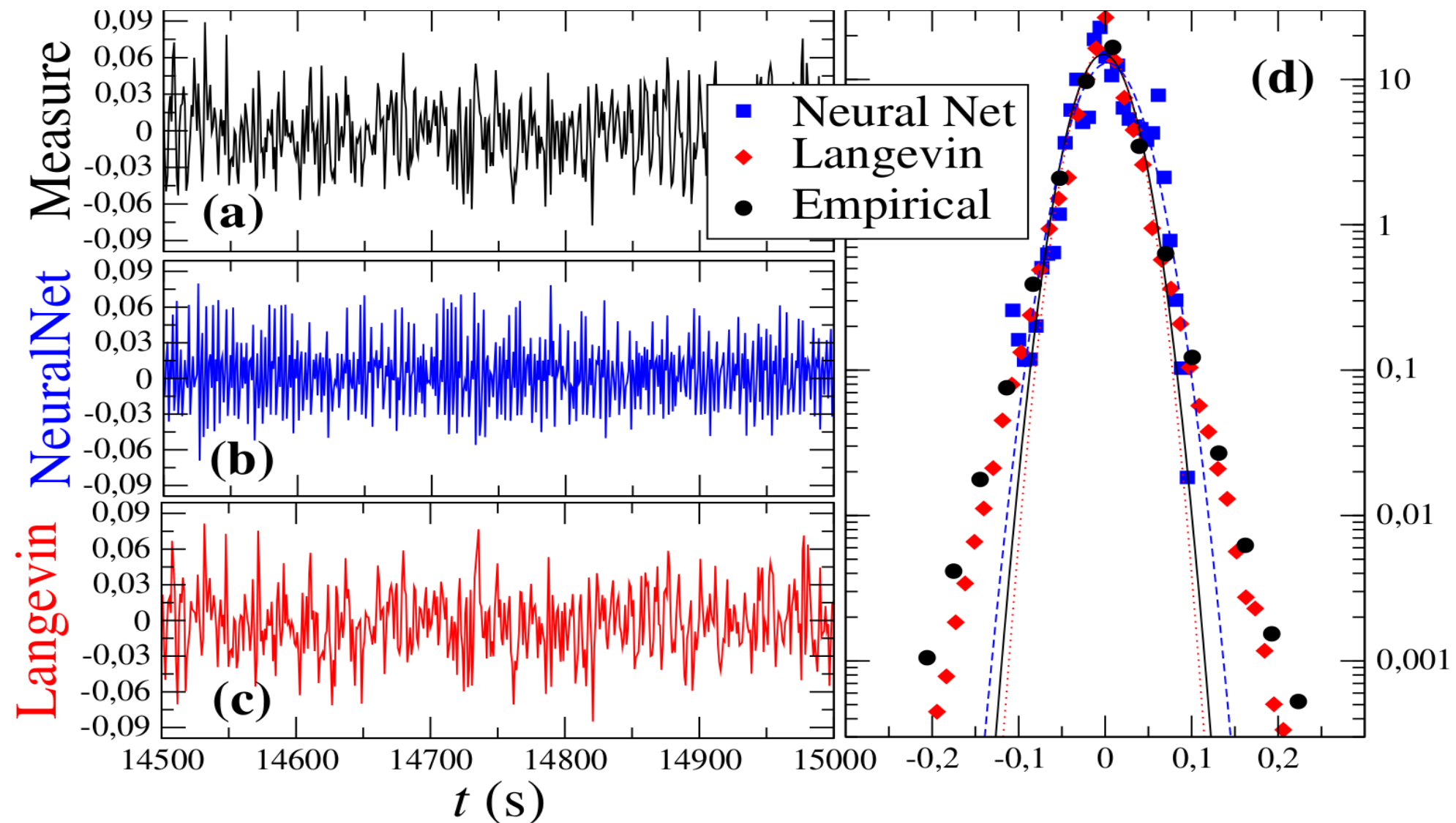
$$\frac{dx}{dt} = D^{(1)}(x) + \sqrt{D^{(2)}(x)}\Gamma_t$$

4. Models prediction



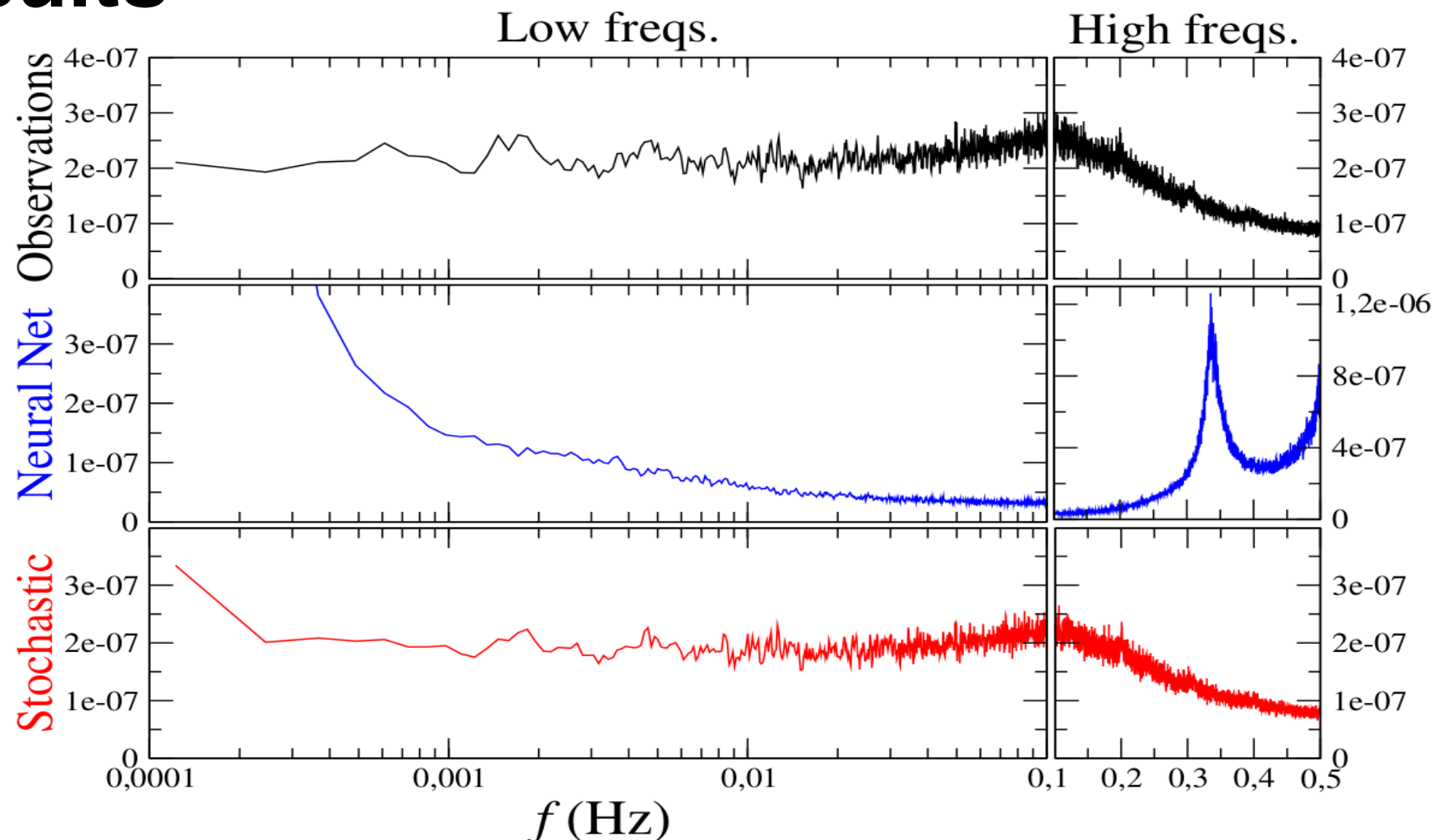
AV 04 – Nov. 2014

5. Results



- Stochastic approach better estimates distribution moments (4th \rightarrow non-gaussian)
- Neural networks reconstructs a Gaussian, original signal is non-gaussian

5. Results



- Reconstructed signals have similar average response
- Neural networks reconstruction does not reproduce frequency content
- Stochastic approach better reconstructs variance in signal
- Frequency content is maintained with stochastic approach

6. Conclusions & outlook

- The stochastic approach is suitable to create normal behaviour models
 - Both methodologies follow similar steps to construct models
 - Neural networks reconstruct central part of original signal
 - Stochastic approach better reconstructs complete frequency content
-
- Stochastic approach available for R: <https://cran.r-project.org/web/packages/Langevin/>
 - Analysis will be extended for different sampling ratios
 - Complete procedure & results will be published

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Appendix



Other results

- Evaluation of bias and variance
- Mean absolute error (MAE)
- Standard deviation of (SD of MAE)

$$\text{MAE} = \frac{1}{n} \sum_{i=1}^n |\hat{y}_i - y_i|$$

$$\text{SD of AE} = \sqrt{\frac{1}{n} \sum_{i=1}^n \left(|\hat{y}_i - y_i| - \frac{1}{n} \sum_{i=1}^n |\hat{y}_i - y_i| \right)^2}$$

- Reconstructed signals have similar average response
- Stochastic approach better reconstructs variance from original signal

Approach	MAE [%]	SD of MAE [%]
Neural network	0.0312	0.0315
Stochastic	0.0266	0.0305

Other results

Approach	Mean	Std. Dev.	Skew	Kurtosis
Measurements	-0.0021	0.0267	0.0206	8.8910
Neural network	0.0029	0.0308	0.2139	0.1057
Stochastic	-0.0016	0.0249	-0.0009	3.1993

Inter step differences

