**GIGAWIND** alpha ventus



Global and Local Monitoring of System Dynamics and Grouted Joint Displacements at the Tripod Support Structure in *alpha ventus* 

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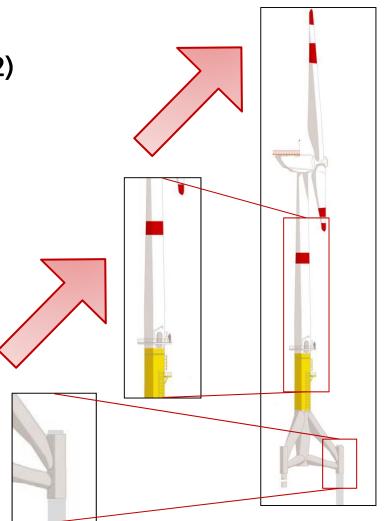






# Content

- I. Monitoring of Grouted Joint (WP2)
  - Motivation
  - Concept and Prototype
  - Recorded Data
- II. Local Monitoring (WP4)
  - Data Assistant
  - Fatigue estimation
- III. Global Monitoring (WP4)
  - Concept & Data basis
  - Modal Analysis
  - Condition Indicators





# MONITORING OF GROUTED JOINT



# Local monitoring at the Grouted Connection

- The Stiffness behavior of Grouted Connections is of high interest
- Displacements between pile and sleeve are needed
  to describe the stiffness behavior
  Adaptable fixing structure
- No existing measuring system is suitable for this field of application
- A new conception was created:
- Sensor protection by an oil-filling
- Flexible magnetically adaptable fixing structure

For Wind W

🜌 Fraunhofer

oil-filled box

Inductive displacement transducer



sleeve

# Manufacturing and Application

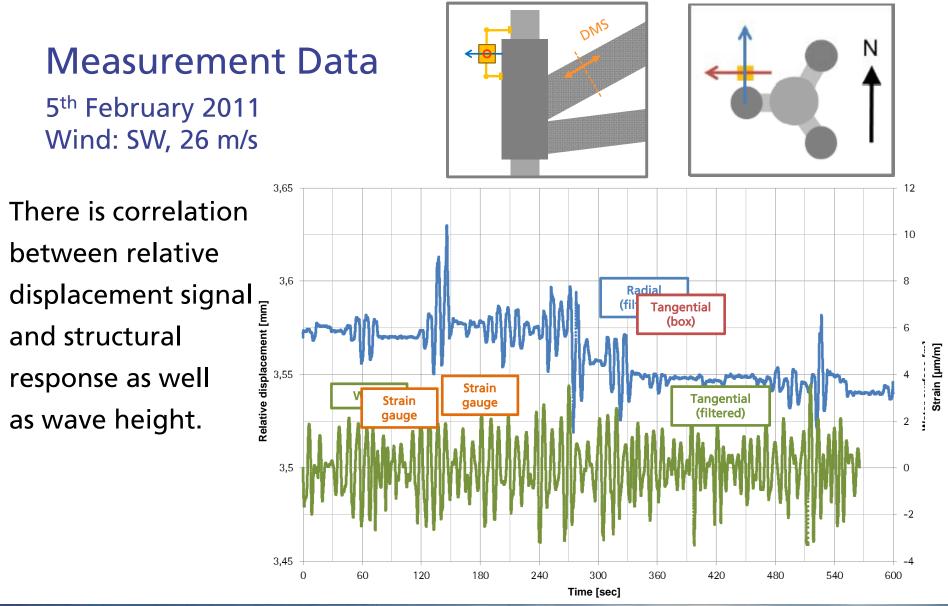
Installed measurement equipment:

- 4 Inductive displacement transducers (2 vertical, 2 horizontal)
- 2 dummy displacement transducers with constant measurement signals
- 1 temperature sensor
- 1 leakage measurement

Application offshore: 11<sup>th</sup> August 2010 Start of data transmission: 2<sup>nd</sup> November 2010









# LOCAL MONITORING



## Measurement Data Assistant

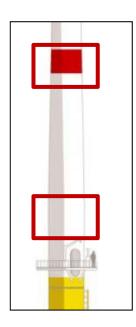
- Goals:
  - Classify and categorize raw data from RAVE data archive
  - Provide a search function for certain load events
  - Provide a means to directly use measurement data in data analysis software without having to download them first
- Setup:
  - Server-based solution
  - Measurement data and search indexes are stored in efficient directory structure
  - **Stateless Access** via HTTP (searches are traceable)
  - Data is streamed to the client, no preparation of downloads necessary
  - All data are exchanged in structured plain text (CSV, JSON)



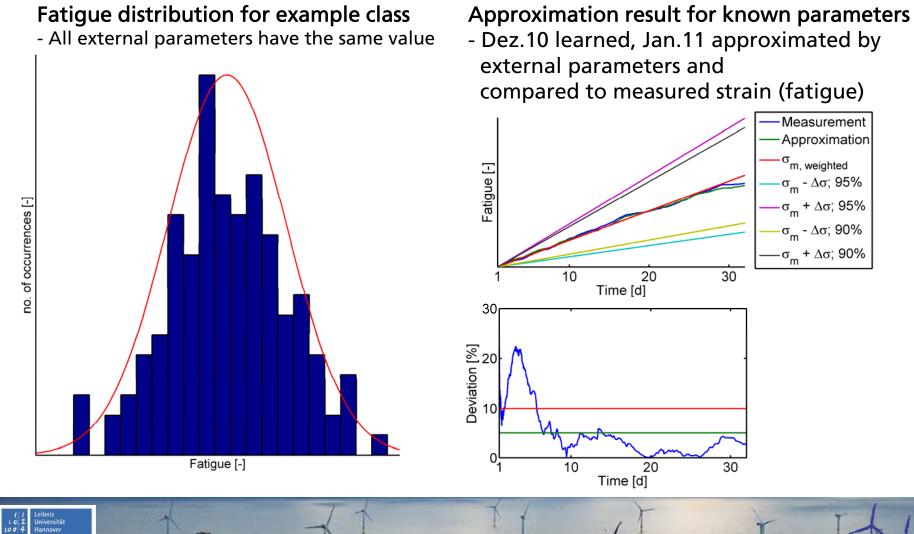
# Fatigue approximation

- Fatigue depends on external parameters
  - External parameters depend on each other
  - Fatigue must be considered depending on combination of external parameters
- Goal: Approximation of fatigue for three cases
  - 1. Known parameters of time period in question
  - 2. Approximation for neighbouring turbine in same period
  - 3. Prognosis of the future
- Method: Fatigue approximation with a Monte Carlo approach
  - Determination of per-class distribution of fatigue (Rainflow, Palmgren-Miner)
  - Classification of parameters of base period and period in question
  - Approx. without strain measurements: Monte Carlo simulation of fatigue using computed distributions with classified parameters in question
  - For prognosis: distribution of parameter classes for base period and their sequence (Markov chain), simulation of possible future parameters using a Markov-chain-Monte-Carlo method



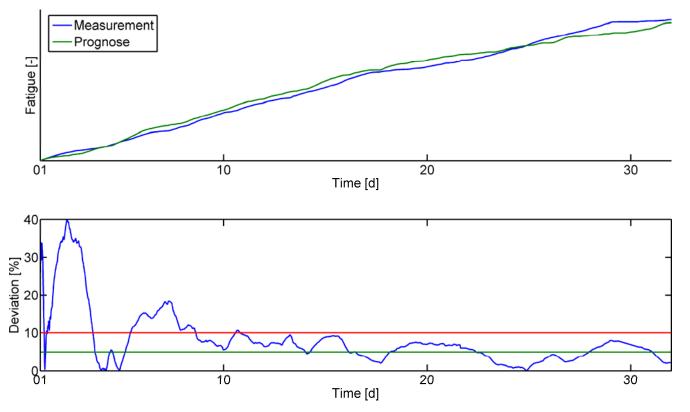


## Fatigue approximation, results





# Approximation result for unknown parameters



Fatigue prognose with MCMC simulation of external parameters
 Dez.10 learned, Jan.11 approximated without external parameters and

compared to measured strain (fatigue)



# **GLOBAL MONITORING**



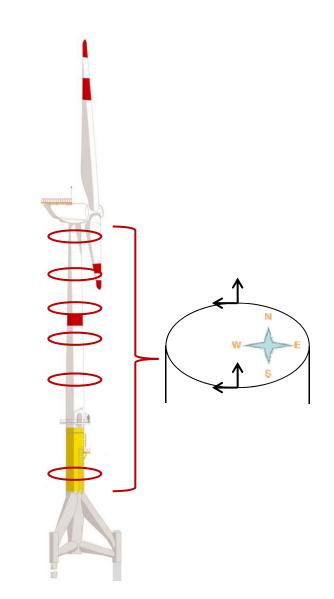
# Concept to analyze the huge data basis

#### Goals:

- Extraction of **modal parameters** for damage localization and quantification
- Extraction of condition parameters (damage existence)

#### Data pool from *alpha ventus*.

- Period: February 2010 June 2011 / 17 Month
- Volume: 1000 GB in binary .mat files
- **48.000 Datasets** of 10 min length each holding
  - 50Hz data of 44 Acceleration sensors and 4 Strain gauges
  - plus Environmental and Operational Conditions (EOCs)





# Concept to analyze the huge data basis

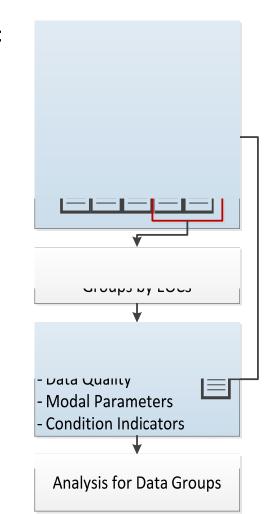
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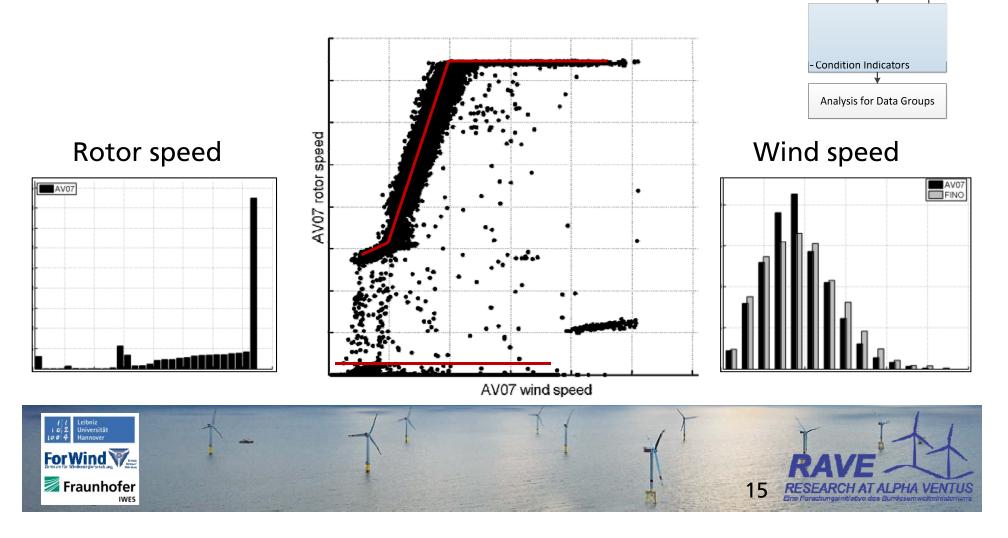
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# Grouping all data sets by EOCs

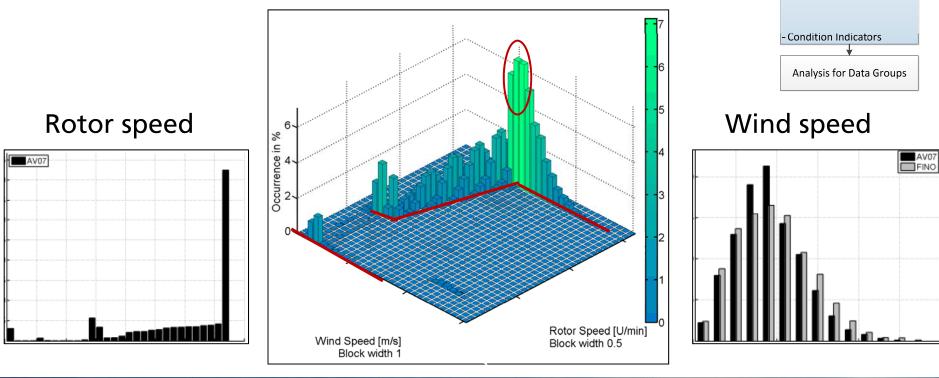
- Here exemplarily EOCs: Rotor speed and wind speed
- Occurrence important for combining data sets to Groups



Groups by EOCs

## Grouping all data sets by EOCs

- Here exemplarily EOCs: Rotor speed and wind speed
- Occurrence important for Selection of sets to Groups
- In the following slides: One Group with 1596 sets



Groups by EOCs



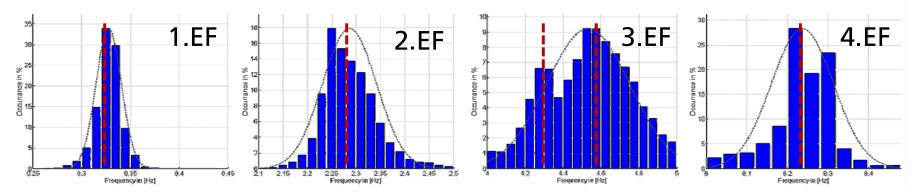
### Modal Analysis for selected data group -1596 sets

- Eigenfrequencies and mode shapes are important values for Damage detection and model validation
- In total: 20 Channels at five different levels were used
- Used Method: Data driven Stochastic Subspace Identification (SSI) for several model orders. Hence, more solutions than phys. modes; a distinction between mathematical and physical solution is needed

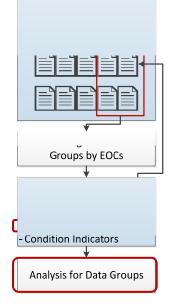


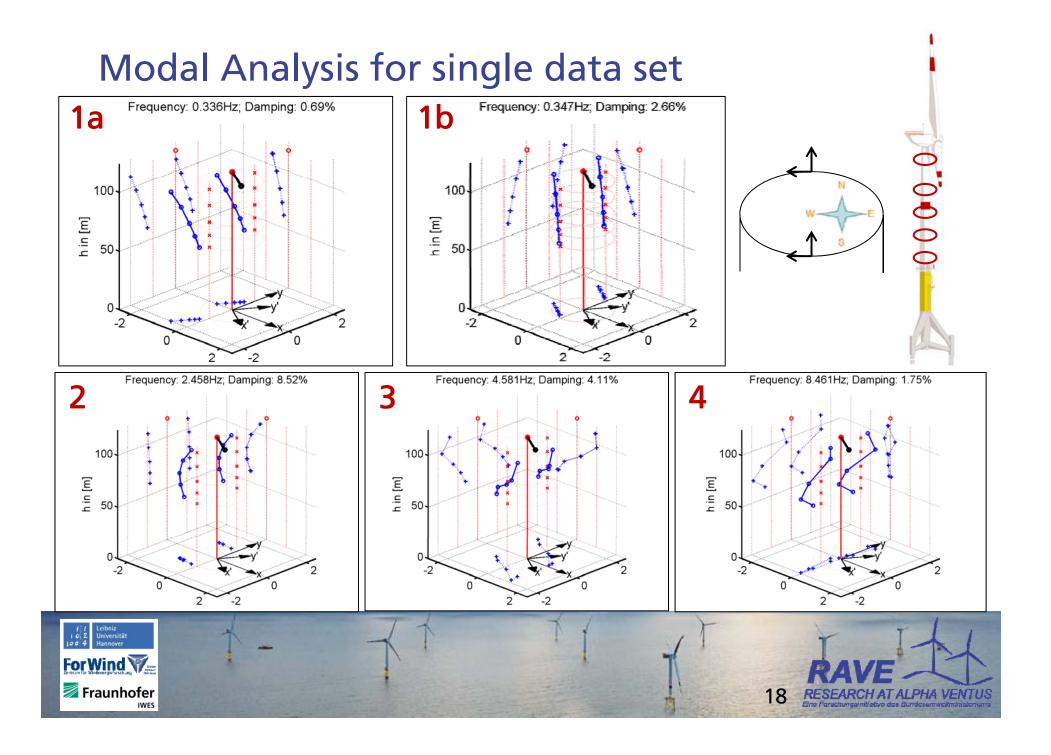
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Projection into nacelle KOS supports interpretation



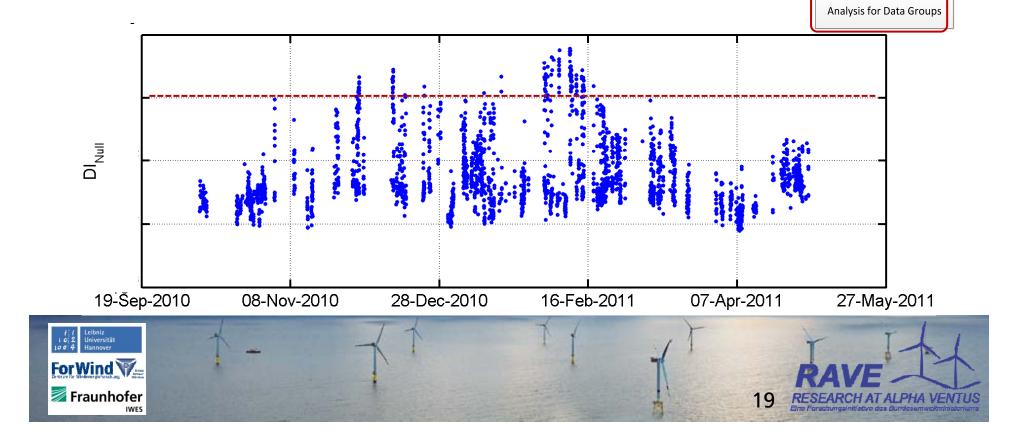






# Condition Indicators give an idea about th structures state

 DI<sub>Null</sub>: Indicator from Covariance driven SSI. A left Nulls pace is calculated for the covariance Block-Hankel-Matrix and compared between reference set and further sets

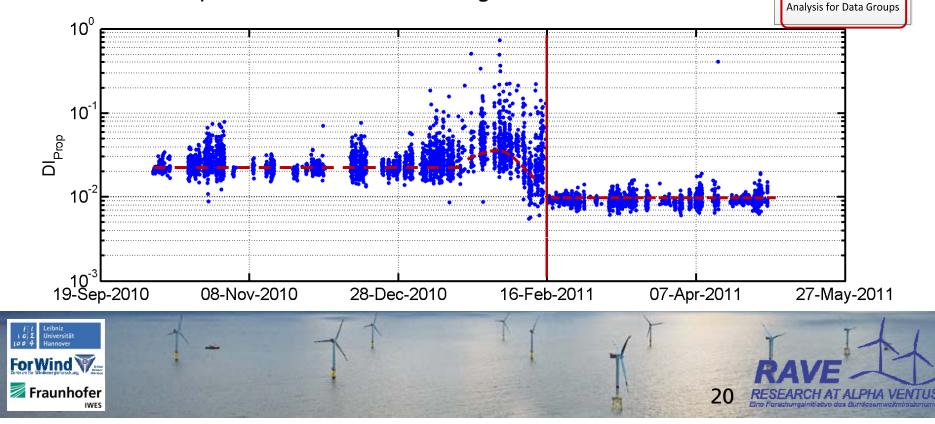


Groups by EOCs

Condition Indicators

# Condition Indicators give an idea about the existence of damage

- DI<sub>Null</sub>: Indicator from Covariance driven SSI. A left Nulls pace is calculated for the covariance Block-Hankel-Matrix and compared between reference set and further sets
- DI<sub>Prop</sub>: Proportionality indicator for comparison of maximal strain level above Tripod and acceleration level below nacelle (both band-pass filtered for first bending mode)



Groups by EOCs

Condition Indicators

# **Conclusions:**

- Grouted Joint
  - Development of prototype measuring device for grouted joint displacements
  - Correlation between external loads (waves) and groutdisplacements
- Local Monitoring
  - Data assistant for quick, local processing of measuring data
  - Calculation, approximation and forecast of fatigue
- Global Monitoring
  - Analysis of global system dynamics for model updating and later damage detection
  - Extraction of condition parameters to distinguish between healthy and unhealthy system states

