

Projekt ParkCast: Optimization of Power-Nowcasting for Offshore-Windfarms using long-range Lidar and Data Assimilation

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RAVE Workshop, 11.05.2023

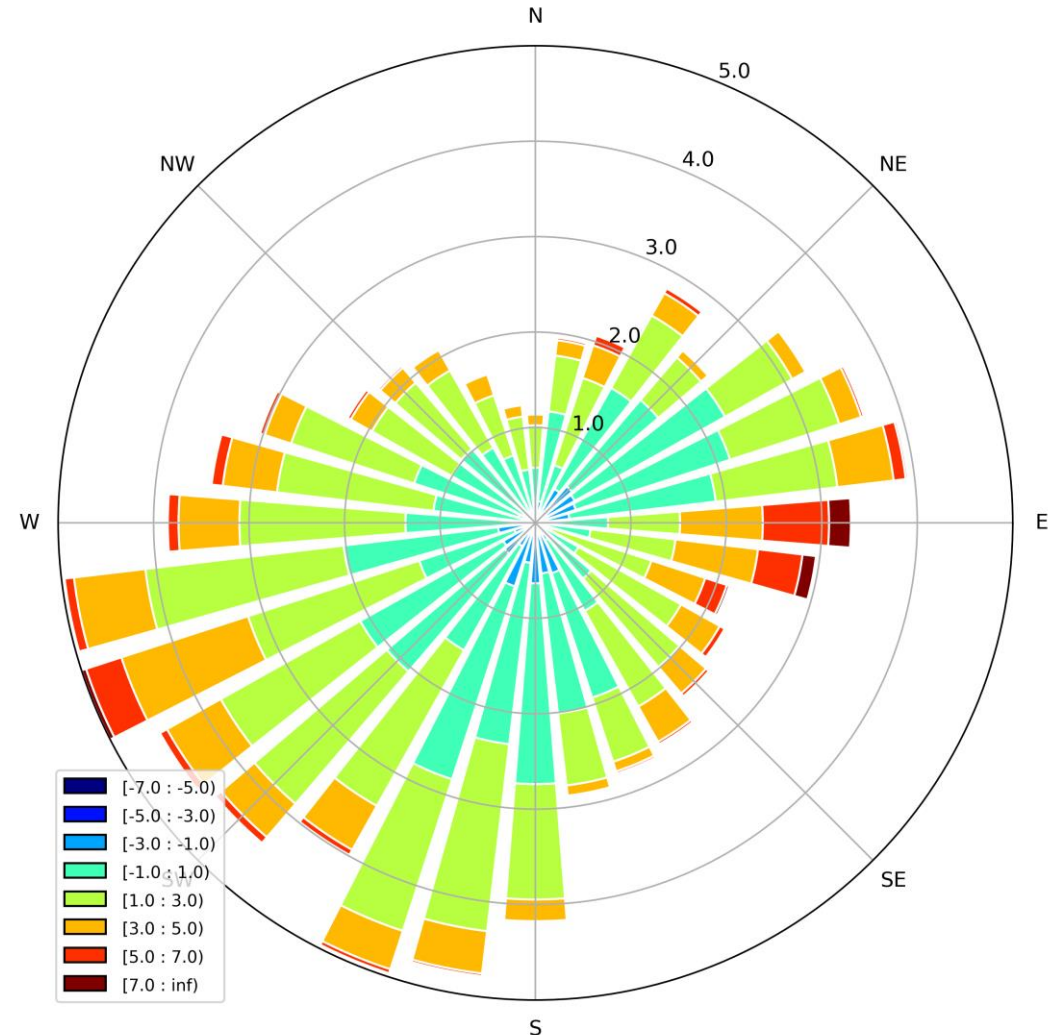


Motivation

On a time scale of minutes to hours...

- **Power generation** of wind turbines can be **highly variable**.
- Causes:
 - Ramp Events
 - Wake Effects due to nearby turbines
- These events are notoriously difficult to predict accurately using numerical models.

Observations from upstream is required → remote sensing.



- Model Errors of wind speed (WRF – FINO1, 1 Year of Simulation)

What is needed?

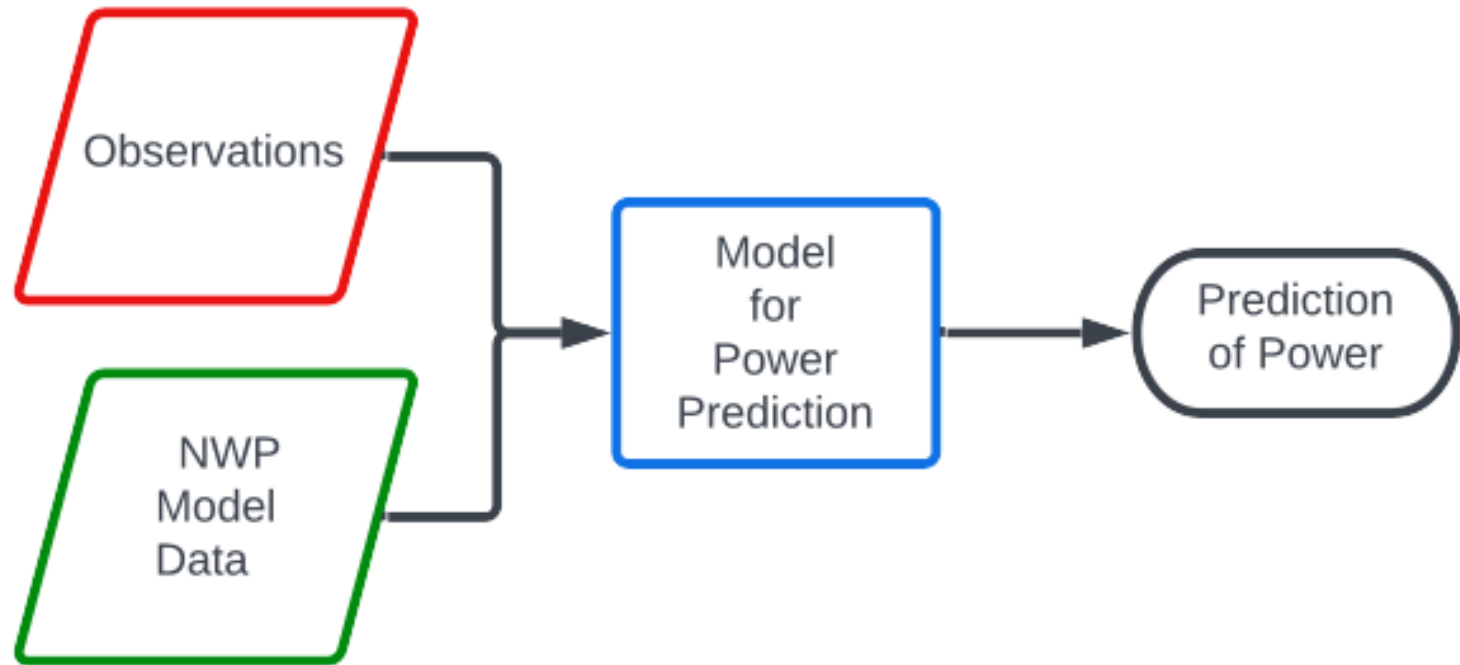
Observations: Long Ranged LIDAR

- Long Ranged (≥ 10 km)
- Observe at least wind speed at hub height.
- Reliable and fast data transmission.

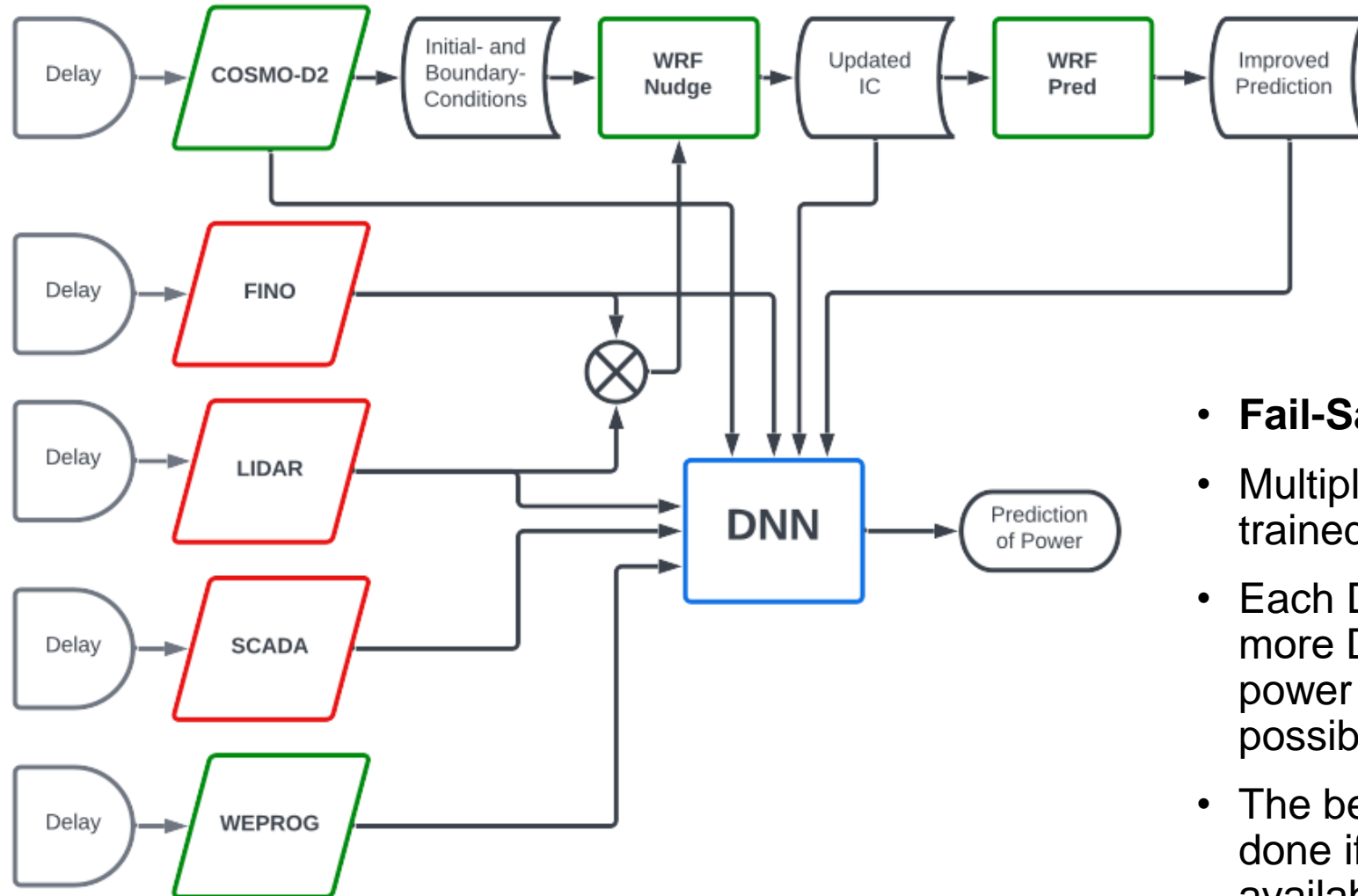
- **NWP Model Data**

- Used to complement incomplete or missing Obs.
- Used as a fallback

- **Model**
- Accurate & Sharp
- **Fast**
- Reliable



Nowcasting Process Chain



- **Fail-Save Design**
- Multiple DNN have been trained
- Each DNN is missing one or more Data sources. → A power prediction is always possible
- The best prediction can be done if all data sources are available.

Observations and Model Data

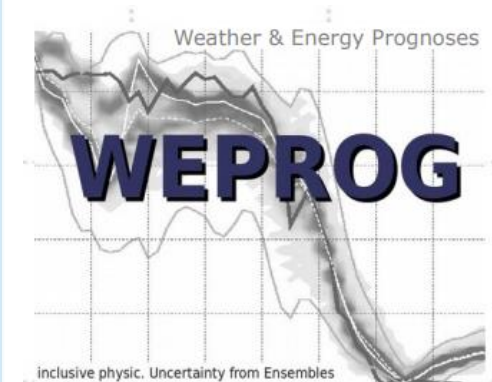
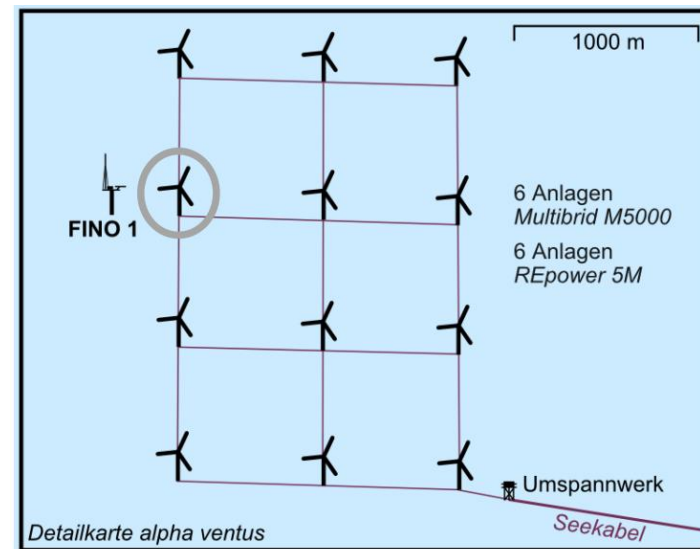
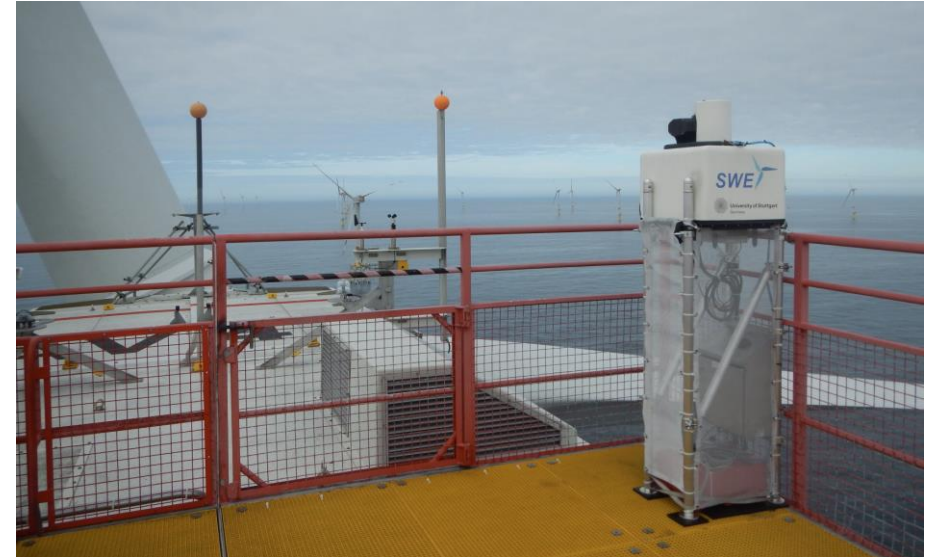
Observations

- Lidar Observations: SWE (Univ. Stuttgart)
- FINO1 – Data: BSH
- SCADA – Data: RAVE Consortium

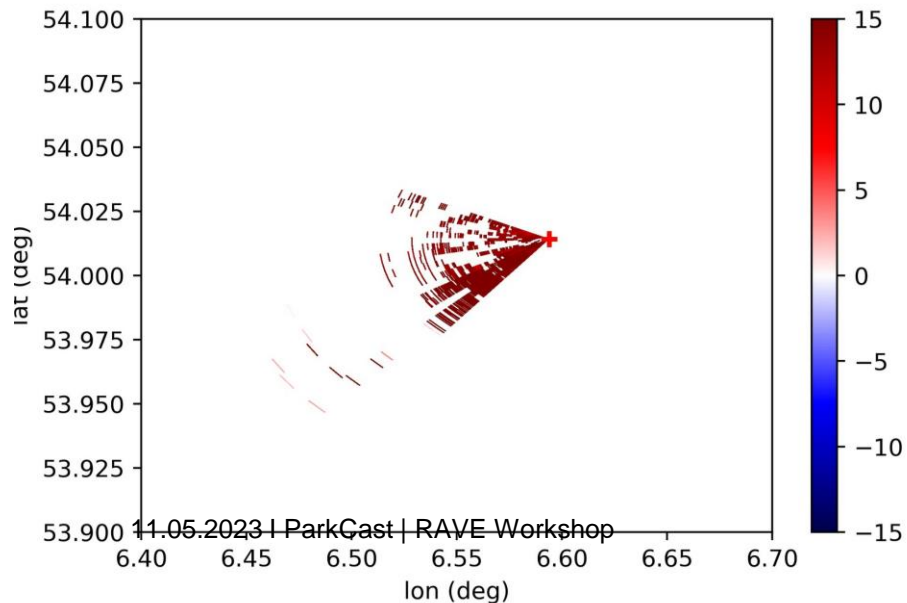
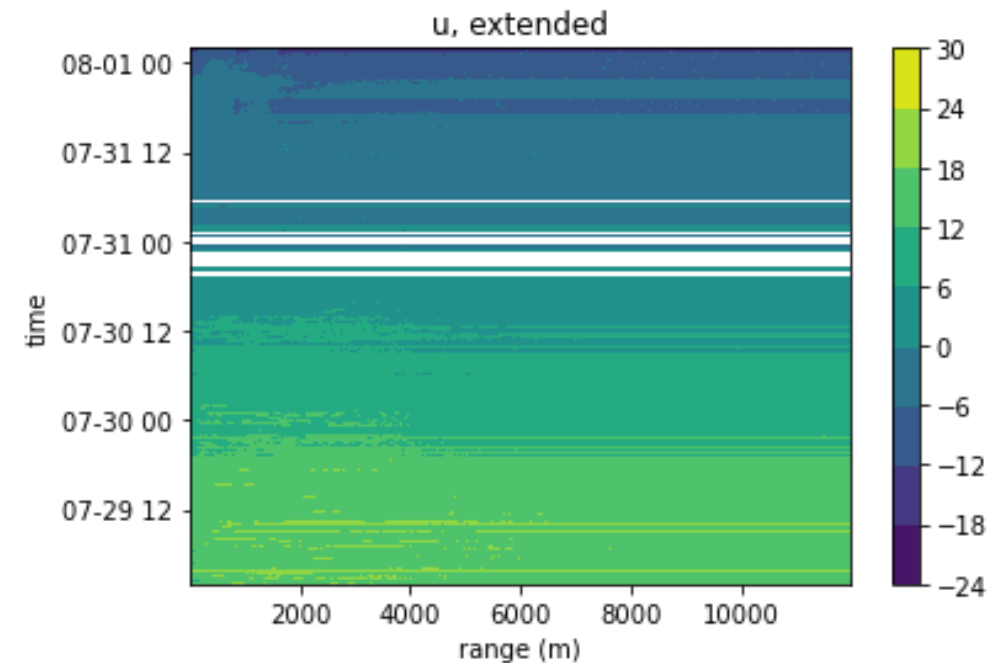
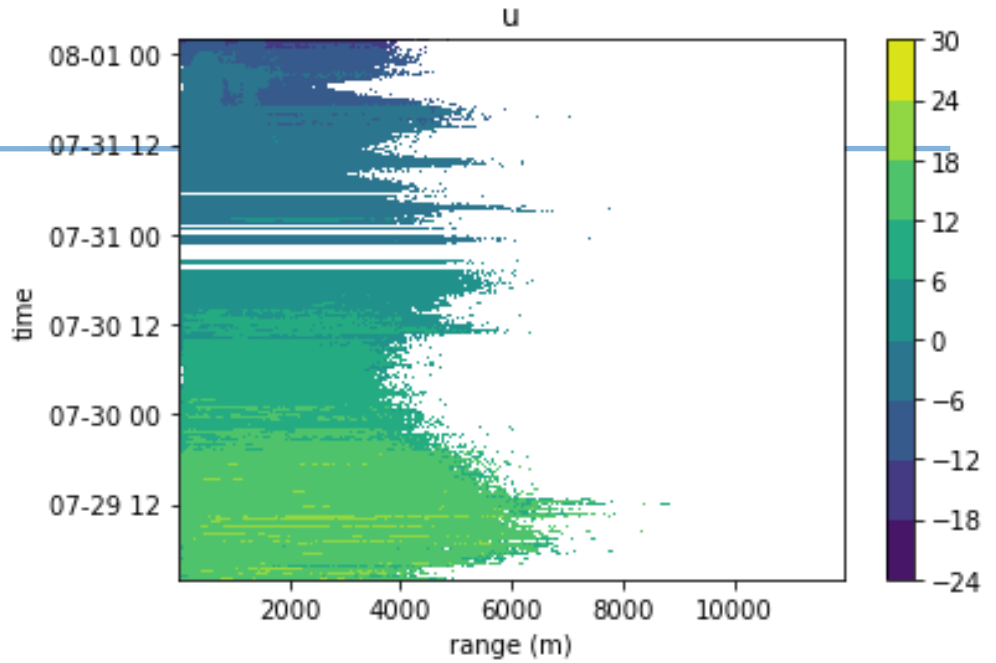
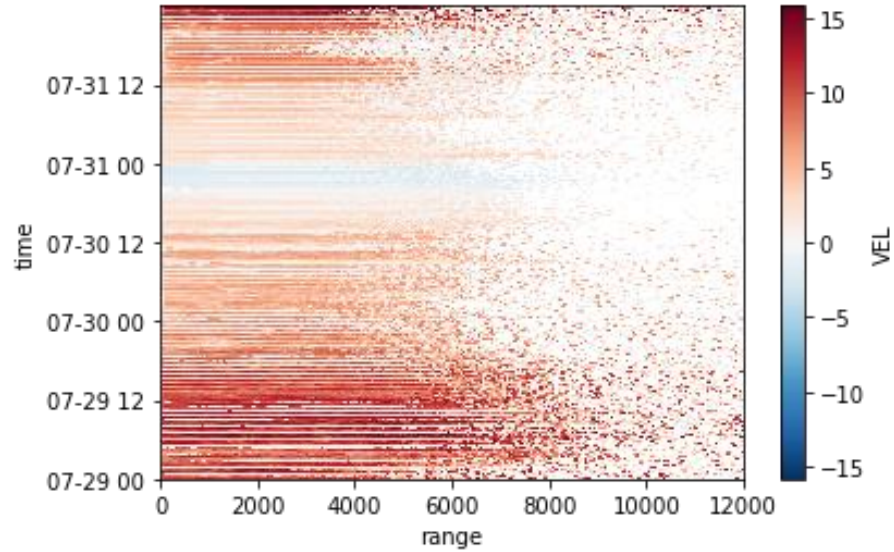
Model Data

- COSMO-2 (DWD) ($\Delta x = 2.2 \text{ km}$)
- WRF-Simulation ($\Delta x = 733.33 \text{ m}$)
- WEPROG Ensemble Data

Multiple data sources as a **safeguard against failure**

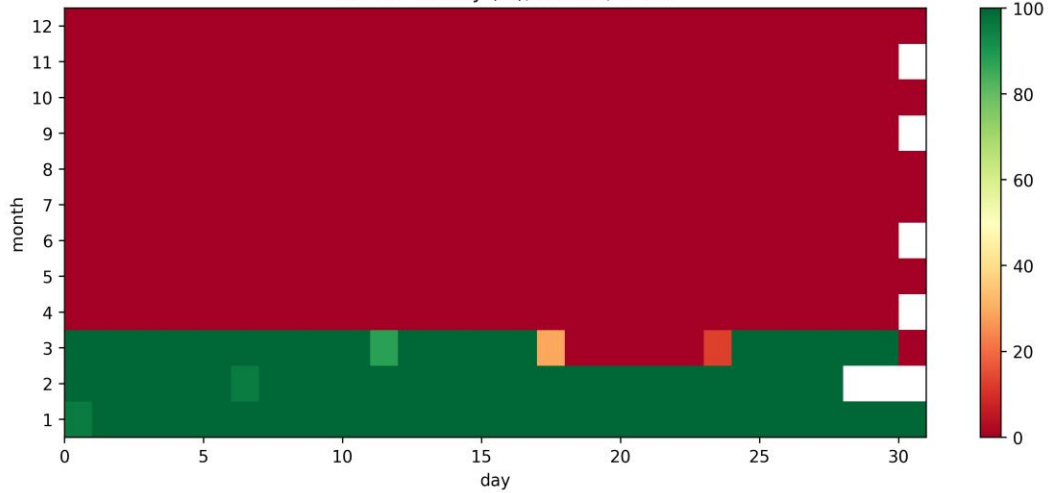


Challenge 1: Processing of Lidar Data

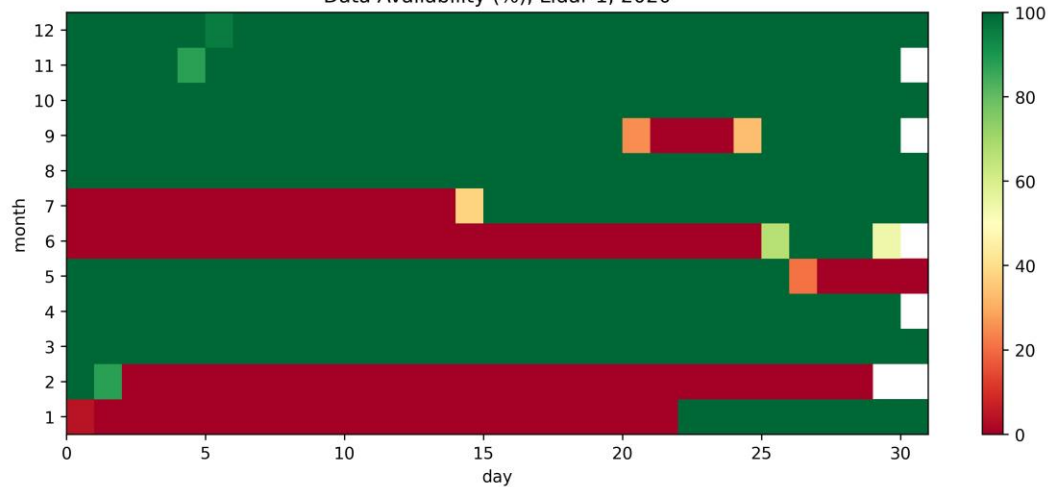


Challenge 2: Data Availability

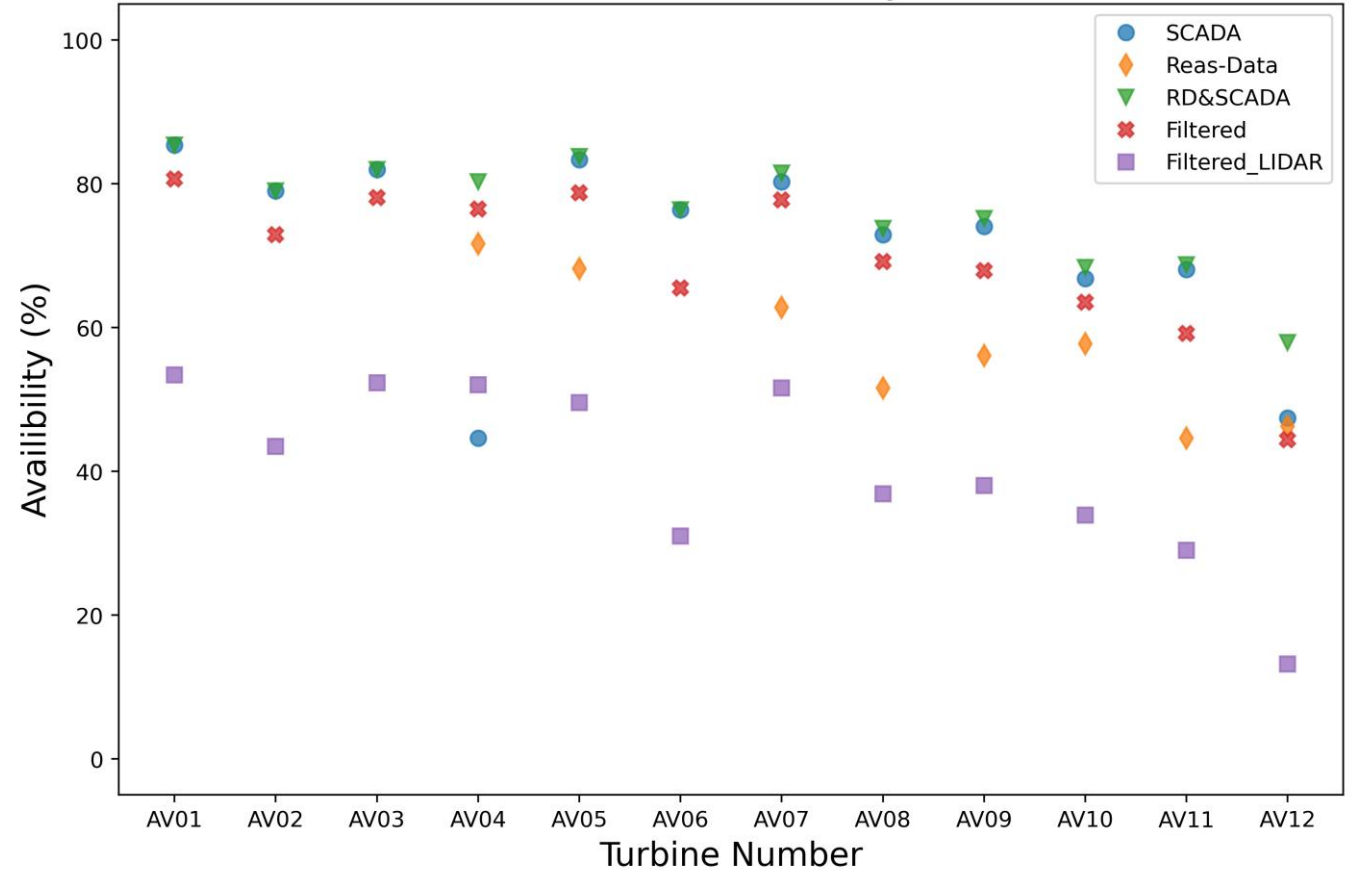
Data Availability (%), Lidar 1, 2021



Data Availability (%), Lidar 1, 2020

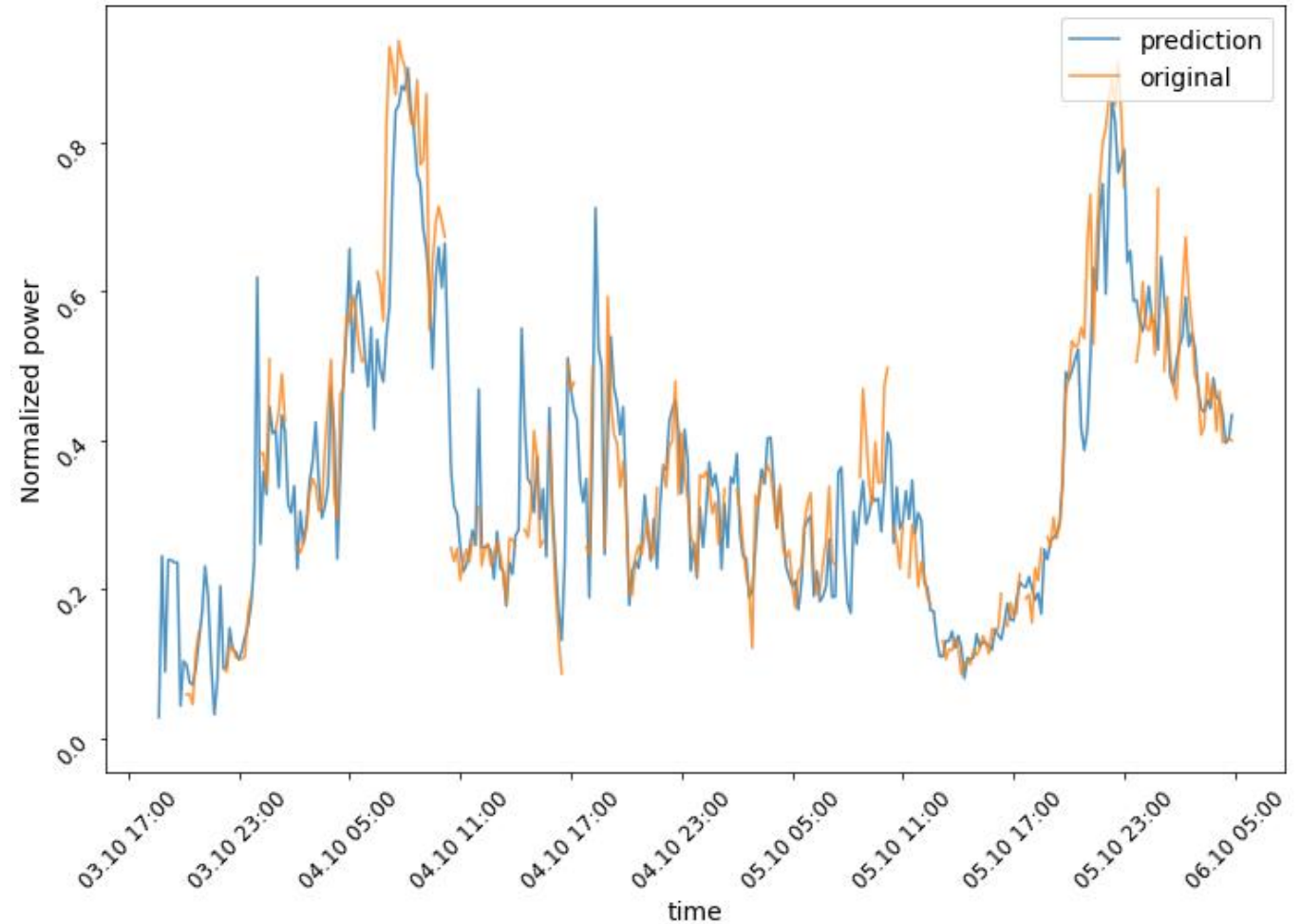
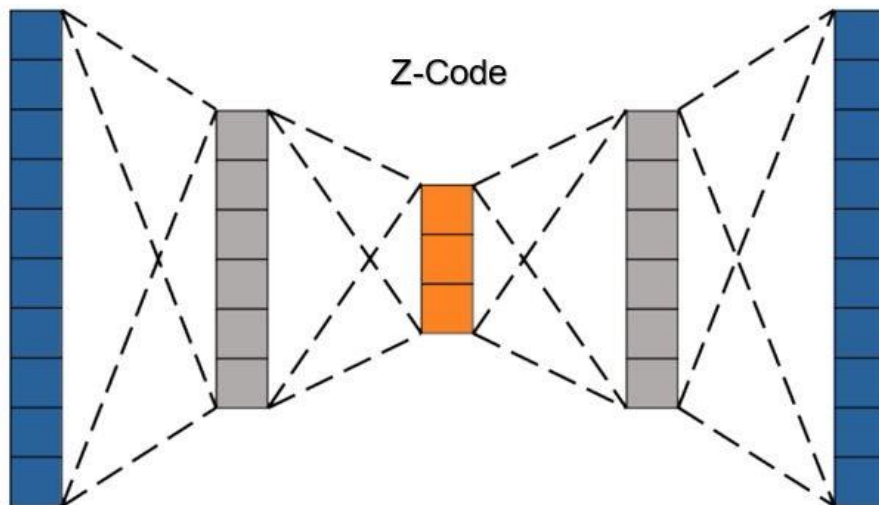


Data Availability

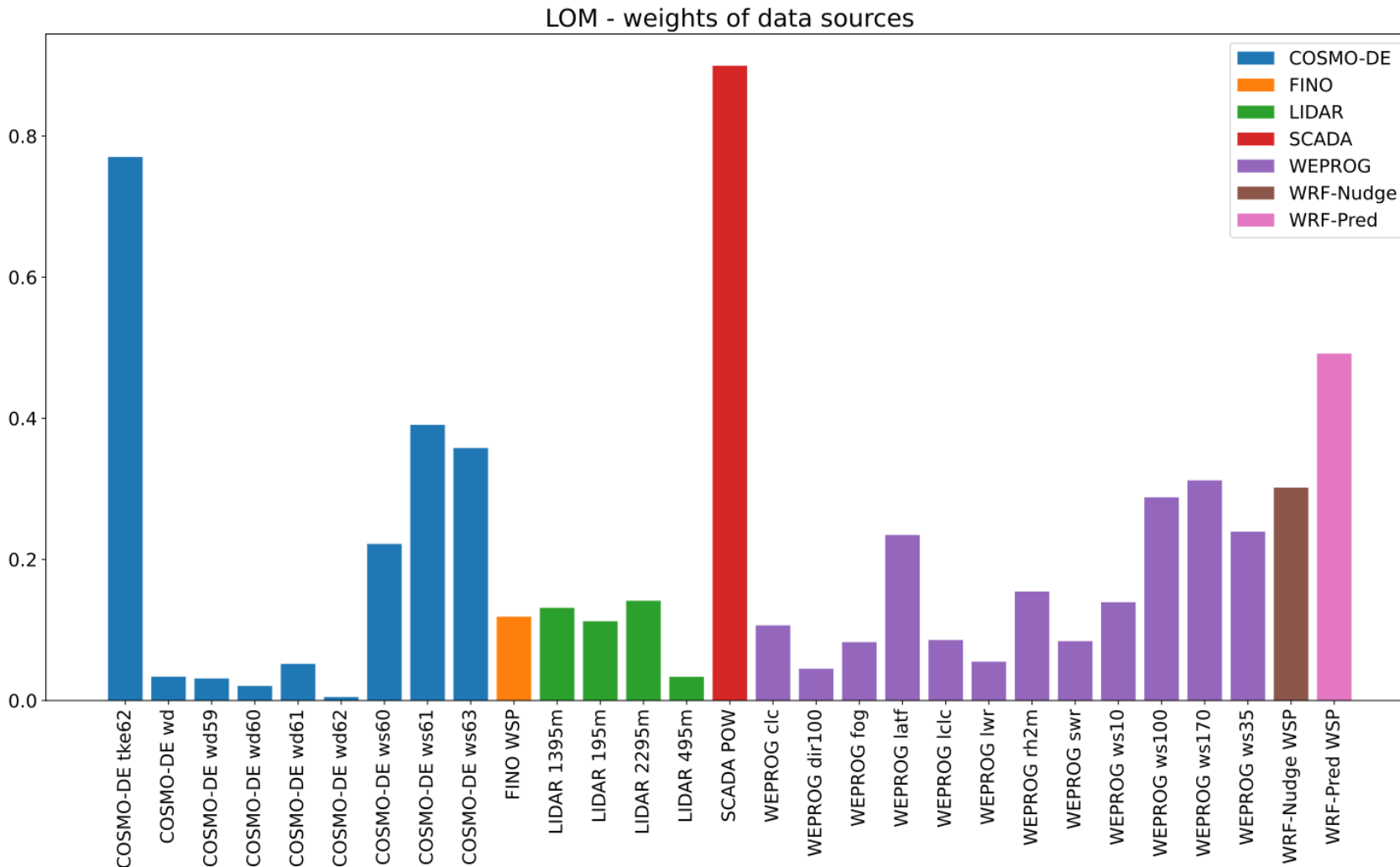


Challenge 2: Data Availability

- Autoencoder approach to fill gaps in available SCADA Data.
- Trained with “good” data only.
- Artificial gaps are put into these time series
- Machine Learning Model trained to fill the gaps with the most likely values based on observed patterns.
- Work only for relatively small gaps.



Training of the DNN: Which data sources are important?

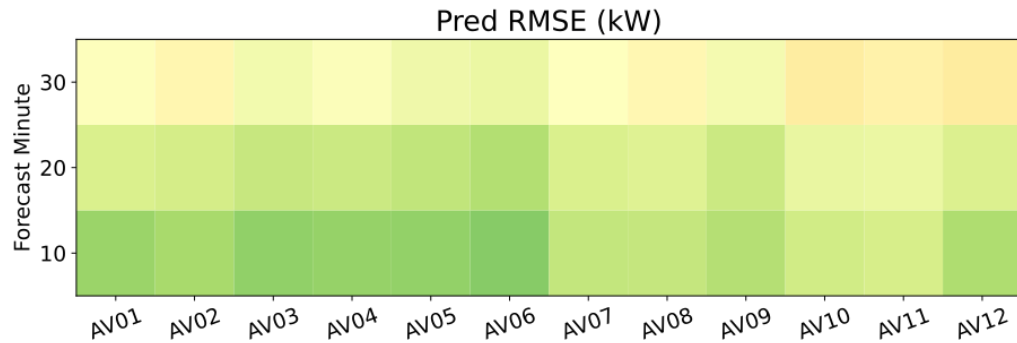
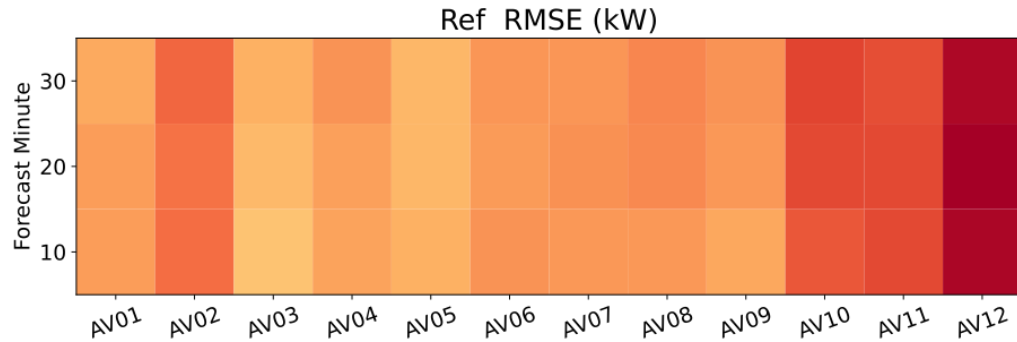


• Feature Selection

- Most important features:
 - SCADA POW,
 - COSMO-D2 TKE & WSP,
 - WRF Model Wind Speed.
- FINO and LIDAR Data are selected as well, but with smaller weights (limited range)
- WEPROG Data contributes considerably

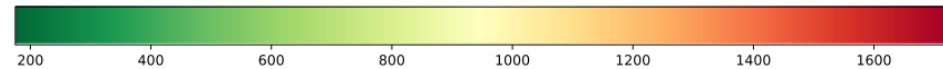
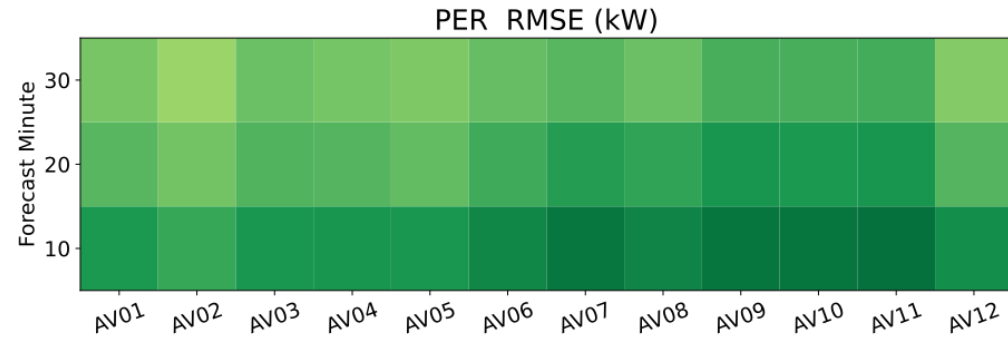
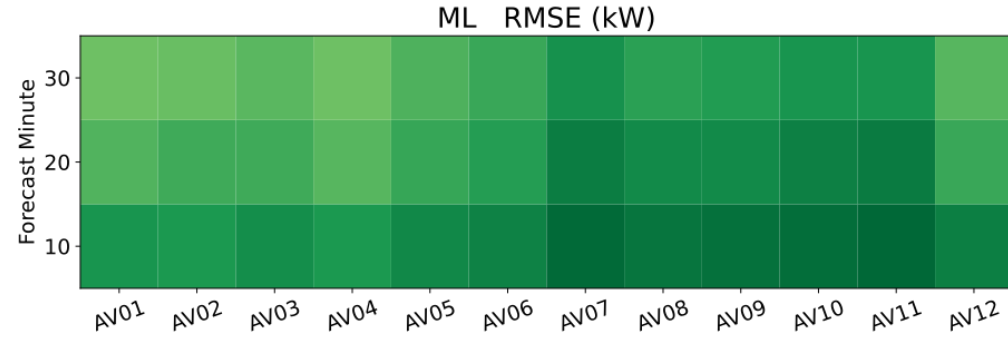
Results

Reference: unmodified WRF



Reference: lidar-nudged WRF

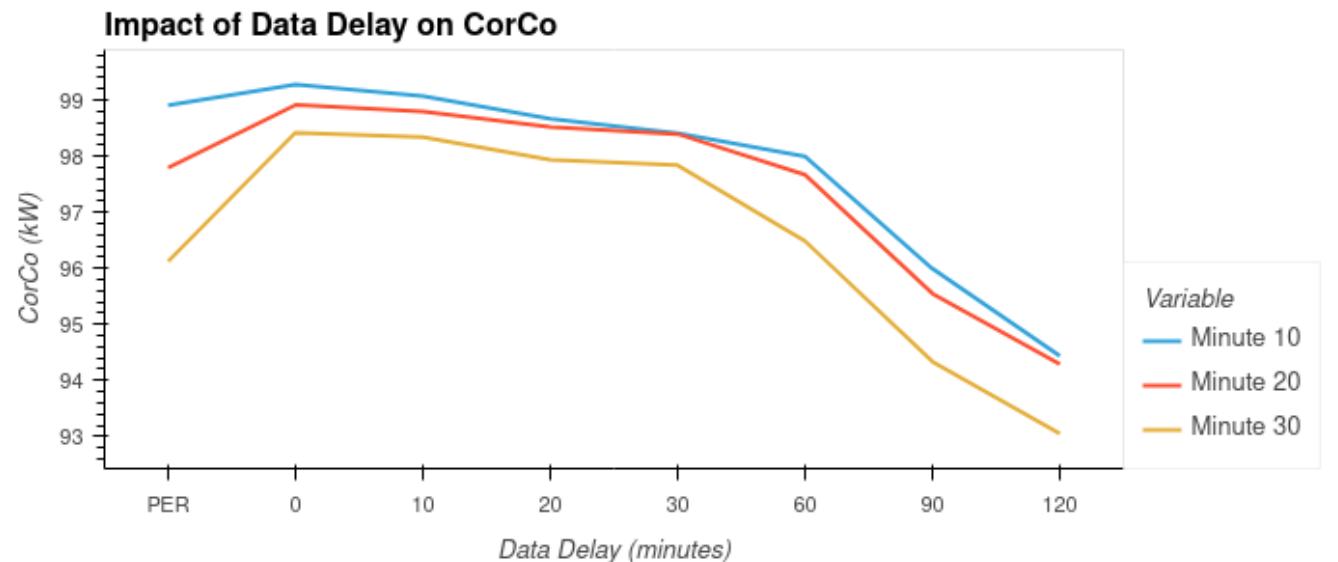
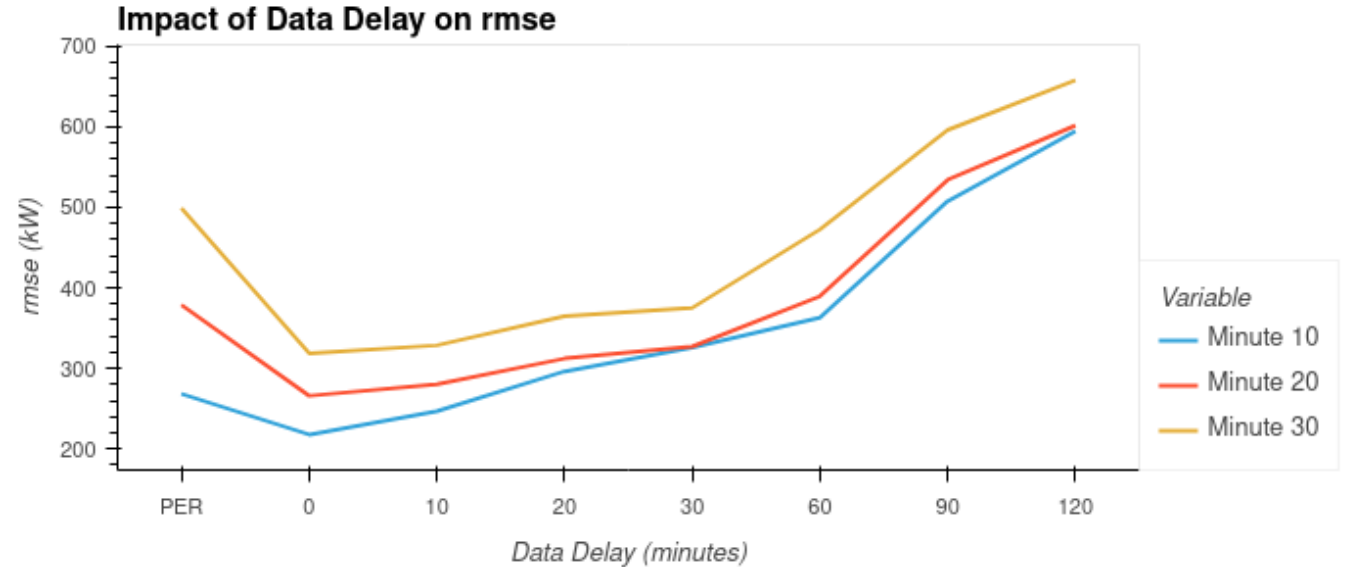
Machine Learning (ML)



Persistence

Challenge 3: Data Delay

- Prediction of Power is better than Persistence for 10 Minute prediction.
- Using old data reduces the quality of the prediction drastically.
- Prediction for t+10 min: **Data should be available as fast as possible.**
- Prediction for t+20 min: Data with 30 Minute delay is still useful
- 10 Minute SCADA data was used as ground truth.



Conclusion

Using Machine Learning and Lidar Observations,

- it is possible to forecast the power production on time-scales $< 1\text{h}$
- with a skill (slightly) better than 10 minute Persistence
- provided the required data is available

Suggestions for future research and development

- Improvements in data availability and training with more data
- Using a lidar with a longer range or a network of lidars.
 - Floating Lidar
 - Lidar on other Turbines
- Cooperation between wind farm operators for data exchange would **enable systems that benefit all.**

ACKNOWLEDGMENTS

The research was financially supported by the **Federal Ministry for Economic Affairs and Energy** (now Federal Ministry for Economic Affairs and Climate Action) contract number (FKZ) 0324330B (ParkCast)



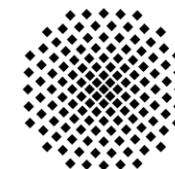
Bundesministerium
für Wirtschaft
und Klimaschutz

Project Partners

- Stuttgarter Lehrstuhl für Windenergie (SWE) – Universität Stuttgart
- WEPROG



Data Providers: RAVE, BSH



Universität Stuttgart