



#### International RAVE Workshop 2022

# Improved domain adaptation for condition monitoring of wind

# turbines

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### Agenda

- Motivation of Domain Adaptation (DA)
- Previous work in wind energy
- Methodology
  - Proposed DA model
  - Baseline DA models
  - Raw data description
- Results
- Next steps



### **Motivation of DA: Examples**

Transfer of an existing estimator from a previous (training) domain to a new target domain.

#### Examples:

- Regression of tire pressure (new vehicle type)
- Regression of belt tension (individual stacker crane)
- Condition monitoring in wind farms

Problems with traditional approches:

- Presumably poor results for non-adapted estimator
- Costly:
  - recording of labelled data of the new (target) domain
  - data pre-processing and model engineering







#### **Motivation of DA: Taxonomy**

Sub-task of Transfer Learning

Requirements / Assumptions:

- 1. same task for both domains
- 2. high amount of labeled data from source domain
- 3.a) only unlabeled data from target domain or
- 3.b) partly labeled data from target domain.

Methodological categorization by *D. Tuia et al. (2016)*:



adapted from S. J. Pan and Q. Yang (2010)



#### **Motivation of DA: Taxonomy**

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### Previous work in wind energy

- DA so far only rarely applied to estimation tasks for wind turbines (first publications towards SHM since 2017)
- P. Gardner et al. (2019) compared two data alignment methods (transfer component analysis (TCA) and joint domain adaptation (JDA)) in order to classify cracks in WT blades.
- W. Juang and J. Jin (2021) used SCADA data to detect blade icing across two domains using a generative adverserial networks (GAN).





### Methodology

Basic estimation tasks:

- Regression of generator power using blades' strain measurements ("academic" task)
- Regression of strain in tower and blade segments using SCADA data
- Ice detection on blades

Wind turbines used (a.k.a. domains):

- AV-07 (Adwen)
- AV-04 (Senvion)

RAVE data used:

• SCADA and blade / tower strain measurements from RAVE research archive

Estimation algorithm:

• MLP (tanh activation, MSE objective, SGD optimization)







#### **Methodology: Data**



#### Domains: AV-07 (Adwen), AV-04 (Senvion)

- tower strain data (DMS, 10 min)
  - lowest tower segment
  - four gauges around tower
- blade strain data (DMS, 10 min)
  - measurment location next to hub
  - flap- and edgewise
- SCADA data (10 min, normalized)
  - rotor speed, wind speed
  - pitch angle
  - eff. generator power
- FINO data (10 min)
  - Environmental and weather data
- Derived variables (planned)
  - Short-term 10 min damages [1]



[1]: Barradas-Berglind, J. J., and Rafael Wisniewski. "Representation of fatigue for wind turbine control." *Wind Energy* 19.12 (2016): 2189-2203.

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### Methodology: Proposed DA model

**Optimal Transport (OT)** 

- Originally used to measure distances between distributions (e.g. Wasserstein distance)
- Growing attention in domain adaptation since ~2015
- Idea: Find (optimal) mapping from  $P(X_s)$  to  $P(X_t)$  (or vice versa) with respect to the shift expense
- Assumptions:
  - homogenious task ( $\gamma_s = \gamma_t$ )
  - no / small target value imbalance  $P(Y_s|X_s) \approx P(Y_t|X_t)$
- Advantage over other data alignment techniques (e.g. PCA, TCA, JDA):
  - non-linear mapping
  - both unsupervised and semi-supervised applications possible
- Algorithm used: Convex group-lasso regularized OT (Sinkhorn-Knopp algorithm)









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#### **Methodology: Baseline DA models**

Other DA methods used for benchmarking:

• No domain adaptation at all:

Applying the source domain trained estimator directly to the target domain

• Feature normalization:

Normalizing each input variable i.o.t. equalize value range across the domains

 Principle component analysis (PCA): Linear data mapping between two domains



### **Results: Strain estimation**

Same estimator (MLP) for all models.

Training data amount: Source (7 months), Target (7 days (unlabeled), 1 day (labeled))

Table 1: Exemplary results (Normalised RMSE) for the estimation of mean tower strain (10 min) using un- and semi-supervised domain adaptation.

Domain Adaptation (direction)	NRMSE for domain adaptation method:					
	no data alignment	Normalization	PCA	Sinkhorn OT (unsupervised)	Sinkhorn OT (semi-supervised)	
AV04 -> AV07	1.699	1.503	0.836	0.178	0.102	
AV07 -> AV04	1.544	0.819	0.922	0.165	0.093	
AV07 only (no DA)	0.058	-	-	-	-	
AV04 only (no DA)	0.076	-	-	-	-	



### **Results: Power estimation**

Same estimator (MLP) for all models.

Training data amount: Source (7 months), Target (7 days (unlabeled), 1 day (labeled))

Table 2: Exemplary results (Normalised RMSE) for the estimation of mean effective power generation (10 min) using un- and semi-supervised domain adaptation.

Domain Adaptation (direction)	NRMSE for domain adaptation method:					
	no data alignment	Normalization	PCA	Sinkhorn OT	Sinkhorn OT (semi-supervised)	
AV04 -> AV07	0.945	0.252	0.179	0.094	0.059	
AV07 -> AV04	0.697	0.115	0.153	0.088	0.075	
AV07 only (no DA)	0.046	-	-	-	-	
AV04 only (no DA)	0.065	-	-	-	-	



#### **Next steps**

- Application to classification tasks (seeking for good examples within RAVE)
- Comparison to state of the art deep learning DA methods (e.g. GAN-based approaches)
- Investigating the influence of the amount of data available (both target and source domain)
- Domain adaptation across different wind farms, not only different wind turbines
  - Stronger target value imbalance  $P(Y_s|X_s) \neq P(Y_t|X_t)$
  - Different sensors  $\Omega_s \neq \Omega_t$





# Thanks for your attention! Questions?

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#### **Appendix: Data periods**

WТ	Start	End	Duration	Function
AV-04	2019-04-01	2020-03-31	366	train
AV-04	2020-08-01	2021-07-31	365	test
AV-07	2016-08-01	2017-07-31	365	train
AV-07	2015-03-01	2015-07-31	153	test
AV-07	2016-11-01	2017-02-28	120	test
AV-07	2020-10-01	2021-02-28	151	train



#### **Appendix: Notation**

Domain D of

- *d*-dimensional (feature) space  $\Omega \in \mathbb{R}^d$  with marginal prob. dist. P(X)
- a task *T* defined by a label space  $\gamma$  and cond. prob. dist. P(Y|X) with (multivariate) random variables *X* and *Y*. Source domain  $D_s = {\Omega_s, P(X_s)}$  with  $T_s = {\gamma_s, P(Y_s|X_s)}$ Target domain  $D_t = {\Omega_t, P(X_t)}$  with  $T_t = {\gamma_t, P(Y_t|X_t)}$

Given a Dataset  $X = \{x_1, ..., x_n\} \in \chi$  with labels  $Y = \{y_1, ..., y_n\} \in \gamma$ , we try finding an estimator  $f(\cdot) = P(Y|X) \approx P(Y|X)$ .

Traditional ML:  $D_s = D_t$  and  $T_s = T_t$ 

Transfer Learning:  $D_s \neq D_t$  or  $T_s \neq T_t$ , examples:

- Class Imbalance: Different label distribution  $P(Y_s) \neq P(Y_t)$ , but at least  $P(X_s|Y_s) = P(X_t|Y_t)$ .
- Covariate Shift:  $P(Y_s|X_s) = P(Y_t|X_t)$ , but (small) difference in data distribution  $P(X_s) \neq P(X_t)$ .

adapted from N. Courty et al. (2017) and G. Csurka (2017)